

VOLUME ONE:

TABLE OF CONTENTS



Chapter 1: Getting Started

Introduction	1-2
The Purpose of this Manual	1-2
Supplemental Manuals	1-2
Technical Support	1-2
Conventions Used	1-3
Key Topics for Each Chapter	1-3
DL06 Micro PLC Overview	1-4
The DL06 PLC Features	1-4
DirectSOFT 5 Programming for Windows™	1-4
Handheld Programmer	1-5
I/O Quick Selection Guide	1-5
Quick Start	1-6
Steps to Designing a Successful System	1-10
Questions and Answers about DL06 Micro PLCs	1-12

Chapter 2: Installation, Wiring, and Specifications

Safety Guidelines	2-2
Plan for Safety	2-2
Three Levels of Protection	2-3
Emergency Stops	2-3
Emergency Power Disconnect	2-4
Orderly System Shutdown	2-4
Class 1, Division 2 Approval	2-4
Orientation to DL06 Front Panel	2-5
Terminal Block Removal	2-6

Table of Contents

Mounting Guidelines	2-7
Unit Dimensions	2-7
Enclosures	2-7
Panel Layout & Clearances	2-8
Using Mounting Rails	2-9
Environmental Specifications	2-10
Agency Approvals	2-10
Marine Use	2-10
Wiring Guidelines	2-11
Fuse Protection for Input Power	2-11
External Power Source	2-12
Planning the Wiring Routes	2-12
Fuse Protection for Input and Output Circuits	2-13
I/O Point Numbering	2-13
System Wiring Strategies	2-14
PLC Isolation Boundaries	2-14
Connecting Operator Interface Devices	2-15
Connecting Programming Devices	2-15
Sinking / Sourcing Concepts	2-16
I/O “Common” Terminal Concepts	2-17
Connecting DC I/O to “Solid State” Field Devices	2-18
Solid State Input Sensors	2-18
Solid State Output Loads	2-18
Relay Output Wiring Methods	2-20
Surge Suppression For Inductive Loads	2-21
Prolonging Relay Contact Life	2-22
DC Input Wiring Methods	2-23
DC Output Wiring Methods	2-24
High-Speed I/O Wiring Methods	2-25
Wiring Diagrams and Specifications	2-26
D0-06AA I/O Wiring Diagram	2-26
D0-06AR I/O Wiring Diagram	2-28
D0-06DA I/O Wiring Diagram	2-30
D0-06DD1 I/O Wiring Diagram	2-32
D0-06DD2 I/O Wiring Diagram	2-34
D0-06DR I/O Wiring Diagram	2-36
D0-06DD1-D I/O Wiring Diagram	2-38

D0-06DD2-D I/O Wiring Diagram	2-40
D0-06DR-D I/O Wiring Diagram	2-42
Glossary of Specification Terms	2-44

Chapter 3: CPU Specifications and Operation

Introduction	3-2
DL06 CPU Features	3-2
CPU Specifications	3-3
CPU Hardware Setup	3-4
Communication Port Pinout Diagrams	3-4
Connecting the Programming Devices	3-5
CPU Setup Information	3-5
Status Indicators	3-6
Mode Switch Functions	3-6
Changing Modes in the DL06 PLC	3-7
Mode of Operation at Power-up	3-7
Using Battery Backup	3-8
Battery Backup	3-8
Auxiliary Functions	3-9
Clearing an Existing Program	3-9
Initializing System Memory	3-9
Setting Retentive Memory Ranges	3-10
Using a Password	3-11
CPU Operation	3-12
CPU Operating System	3-12
Program Mode	3-13
Run Mode	3-13
Read Inputs	3-14
Service Peripherals and Force I/O	3-14
CPU Bus Communication	3-15
Update Clock, Special Relays and Special Registers	3-15
Solve Application Program	3-16
Solve PID Loop Equations	3-16
Write Outputs	3-16
Write Outputs to Specialty I/O	3-16
Diagnostics	3-17

Table of Contents

I/O Response Time	3-17
Is Timing Important for Your Application?	3-17
Normal Minimum I/O Response	3-18
Normal Maximum I/O Response	3-18
Improving Response Time	3-19
CPU Scan Time Considerations	3-20
Reading Inputs	3-20
Writing Outputs	3-20
Service Peripherals	3-21
CPU Bus Communication	3-21
Update Clock/Calendar, Special Relays, Special Registers	3-21
Application Program Execution	3-22
PLC Numbering Systems	3-23
PLC Resources	3-23
V-Memory	3-24
Binary-Coded Decimal Numbers	3-24
Hexadecimal Numbers	3-24
Memory Map	3-25
Octal Numbering System	3-25
Discrete and Word Locations	3-25
V-memory Locations for Discrete Memory Areas	3-25
Input Points (X Data Type)	3-26
Output Points (Y Data Type)	3-26
Control Relays (C Data Type)	3-26
Timers and Timer Status Bits (T Data Type)	3-26
Timer Current Values (V Data Type)	3-27
Counters and Counter Status Bits (CT Data type)	3-27
Counter Current Values (V Data Type)	3-27
Word Memory (V Data Type)	3-28
Stages (S Data type)	3-28
Special Relays (SP Data Type)	3-28
DL06 System V-memory	3-29
System Parameters and Default Data Locations (V Data Type)	3-29
DL06 Aliases	3-31
DL06 Memory Map	3-32
X Input/Y Output Bit Map	3-33

Stage Control/Status Bit Map	3-34
Control Relay Bit Map	3-36
Timer Status Bit Map	3-38
Counter Status Bit Map	3-38
GX and GY I/O Bit Map	3-39

Chapter 4: System Design and Configuration

DL06 System Design Strategies	4-2
I/O System Configurations	4-2
Networking Configurations	4-2
Module Placement	4-3
Slot Numbering	4-3
Automatic I/O Configuration	4-4
Manual I/O Configuration	4-4
Power Budgeting	4-5
Power supplied	4-5
Power required by base unit	4-5
Power required by option cards	4-5
Configuring the DL06's Comm Ports	4-7
DL06 Port Specifications	4-7
DL06 Port Pinouts	4-7
Choosing a Network Specification	4-8
RS-232 Network	4-8
RS-422 Network	4-8
RS-485 Network	4-8
Connecting to MODBUS and DirectNET Networks	4-9
MODBUS Port Configuration	4-9
DirectNET Port Configuration	4-10
Non-Sequence Protocol (ASCII In/Out and PRINT)	4-11
Non-Sequence Port Configuration	4-11
Network Slave Operation	4-12
MODBUS Function Codes Supported	4-12
Determining the MODBUS Address	4-12
If Your Host Software Requires the Data Type and Address	4-13

Table of Contents

Example 1: V2100	4-14
Example 2: Y20	4-14
Example 3: T10 Current Value	4-14
Example 4: C54	4-14
If Your MODBUS Host Software Requires an Address ONLY	4-15
Example 1: V2100 584/984 Mode	4-17
Example 2: Y20 584/984 Mode	4-17
Example 3: T10 Current Value 484 Mode	4-17
Example 4: C54 584/984 Mode	4-17
Network Master Operation	4-18
Step 1: Identify Master Port # and Slave #	4-19
Step 2: Load Number of Bytes to Transfer	4-19
Step 3: Specify Master Memory Area	4-20
Step 4: Specify Slave Memory Area	4-20
Communications from a Ladder Program	4-21
Multiple Read and Write Interlocks	4-21
Network Master Operation (using MRX and MWX Instructions)	4-22
MODBUS Function Codes Supported	4-22
MODBUS Read from Network(MRX)	4-23
MRX Slave Memory Address	4-24
MRX Master Memory Addresses	4-24
MRX Number of Elements	4-24
MRX Exception Response Buffer	4-24
MODBUS Write to Network (MWX)	4-25
MWX Slave Memory Address	4-26
MWX Master Memory Addresses	4-26
MWX Number of Elements	4-26
MWX Exception Response Buffer	4-26
MRX/MWX Example in DirectSOFT 5	4-27
Multiple Read and Write Interlocks	4-27

Chapter 5: Standard RLL Instructions

Introduction	5-2
Using Boolean Instructions	5-5
END Statement	5-5
Simple Rungs	5-5

Normally Closed Contact	5-6
Contacts in Series	5-6
Midline Outputs	5-6
Parallel Elements	5-7
Joining Series Branches in Parallel	5-7
Joining Parallel Branches in Series	5-7
Combination Networks	5-7
Comparative Boolean	5-8
Boolean Stack	5-8
Immediate Boolean	5-9
Boolean Instructions	5-10
Comparative Boolean	5-26
Immediate Instructions	5-32
Timer, Counter and Shift Register Instructions	5-39
Using Timers	5-39
Timer Example Using Discrete Status Bits	5-41
Timer Example Using Comparative Contacts	5-41
Accumulating Timer Example using Discrete Status Bits	5-43
Accumulator Timer Example Using Comparative Contacts	5-43
Using Counters	5-44
Counter Example Using Discrete Status Bits	5-46
Counter Example Using Comparative Contacts	5-46
Stage Counter Example Using Discrete Status Bits	5-48
Stage Counter Example Using Comparative Contacts	5-48
Up / Down Counter Example Using Discrete Status Bits	5-50
Up / Down Counter Example Using Comparative Contacts	5-50
Accumulator/Stack Load and Output Data Instructions	5-52
Using the Accumulator	5-52
Copying Data to the Accumulator	5-52
Changing the Accumulator Data	5-53
Using the Accumulator Stack	5-54
Using Pointers	5-55
Logical Instructions (Accumulator)	5-69
Math Instructions	5-86
Transcendental Functions	5-118

Table of Contents

Bit Operation Instructions5-120
Number Conversion Instructions (Accumulator)5-127
Shuffle Digits Block Diagram5-139
Table Instructions5-141
Copy Data From a Data Label Area to V-memory5-143
Clock/Calendar Instructions5-171
CPU Control Instructions5-173
Program Control Instructions5-175
Interrupt Instructions5-183
Message Instructions5-186
Move Block Instruction (MOVBLK)5-189
Copy Data From a Data Label Area to V-memory5-189
Intelligent I/O Instructions5-194
Read from Intelligent Module (RD)5-194
Write to Intelligent Module (WT)5-195
Network Instructions5-196
Direct Text Entry5-200
Embedding date and/or time variables5-201
Embedding V-memory data5-201
Data Format Suffixes for Embedded V-memory Data5-202
Text Entry from V-memory5-203
MODBUS RTU Instructions5-204
MRX Slave Address Ranges5-205
MWX Slave Address Ranges5-208
MWX Master Memory Address Ranges5-208
MWX Number of Elements5-208
MWX Exception Response Buffer5-208
ASCII Instructions5-210
Reading ASCII Input Strings5-210
Writing ASCII Output Strings5-210
Managing the ASCII Strings5-211
Intelligent Box (IBox) Instructions5-230

VOLUME TWO:

TABLE OF CONTENTS



Chapter 6: Drum Instruction Programming

Introduction	6-2
Purpose	6-2
Drum Terminology	6-2
Drum Chart Representation	6-3
Output Sequences	6-3
Step Transitions	6-4
Drum Instruction Types	6-4
Timer-Only Transitions	6-4
Timer and Event Transitions	6-5
Event-Only Transitions	6-6
Counter Assignments	6-6
Last Step Completion	6-7
Overview of Drum Operation	6-8
Drum Instruction Block Diagram	6-8
Powerup State of Drum Registers	6-9
Drum Control Techniques	6-10
Drum Control Inputs	6-10
Self-Resetting Drum	6-11
Initializing Drum Outputs	6-11
Using Complex Event Step Transitions	6-11
Drum Instruction	6-12
Timed Drum with Discrete Outputs (DRUM)	6-12
Event Drum (EDRUM)	6-14
Handheld Programmer Drum Mnemonics	6-16

Masked Event Drum with Discrete Outputs (MDRMD)6-19
Masked Event Drum with Word Output (MDRMW)6-21

Chapter 7: RLL^{PLUS} Stage Programming

Introduction to Stage Programming7-2
 Overcoming “Stage Fright”7-2

Learning to Draw State Transition Diagrams7-3
 Introduction to Process States7-3
 The Need for State Diagrams7-3
 A 2-State Process7-3
 RLL Equivalent7-4
 Stage Equivalent7-4
 Let’s Compare7-5
 Initial Stages7-5
 What Stage Bits Do7-6
 Stage Instruction Characteristics7-6

Using the Stage Jump Instruction for State Transitions7-7
 Stage Jump, Set, and Reset Instructions7-7

Stage Program Example: Toggle On/Off Lamp Controller7-8
 A 4-State Process7-8

Four Steps to Writing a Stage Program7-9
 1. Write a Word Description of the application.7-9
 2. Draw the Block Diagram.7-9
 3. Draw the State Transition Diagram.7-9
 4. Write the Stage Program.7-9

Stage Program Example: A Garage Door Opener7-10
 Garage Door Opener Example7-10
 Draw the Block Diagram7-10
 Draw the State Diagram7-11
 Add Safety Light Feature7-12
 Modify the Block Diagram and State Diagram7-12
 Using a Timer Inside a Stage7-13
 Add Emergency Stop Feature7-14
 Exclusive Transitions7-14

Stage Program Design Considerations7-15

Stage Program Organization	7-15
How Instructions Work Inside Stages	7-16
Using a Stage as a Supervisory Process	7-17
Stage Counter	7-17
Power Flow Transition Technique	7-18
Stage View in DirectSOFT 5	7-18
Parallel Processing Concepts	7-19
Parallel Processes	7-19
Converging Processes	7-19
Convergence Stages (CV)	7-19
Convergence Jump (CVJMP)	7-20
Convergence Stage Guidelines	7-20
RLL^{PLUS} (Stage) Instructions	7-21
Stage (SG)	7-21
Initial Stage (ISG)	7-22
Jump (JMP)	7-22
Not Jump (NJMP)	7-22
Converge Stage (CV) and Converge Jump (CVJMP)	7-23
Block Call (BCALL)	7-25
Block (BLK)	7-25
Block End (BEND)	7-25
Questions and Answers about Stage Programming	7-27
Chapter 8: PID Loop Operation	
DL06 PID Control	8-2
DL06 PID Control Features	8-2
Introduction to PID Control	8-4
What is PID Control?	8-4
Introducing DL06 PID Control	8-6
Process Control Definitions	8-8
PID Loop Operation	8-9
Position Form of the PID Equation	8-9
Reset Windup Protection	8-10
Freeze Bias	8-11
Adjusting the Bias	8-11

Table of Contents

Step Bias Proportional to Step Change in SP	.8-12
Eliminating Proportional, Integral or Derivative Action	.8-12
Velocity Form of the PID Equation	.8-12
Bumpless Transfer	.8-13
Loop Alarms	.8-13
Loop Operating Modes	.8-14
Special Loop Calculations	.8-14
Ten Steps to Successful Process Control	.8-16
PID Loop Setup	.8-18
Some Things to Do and Know Before Starting	.8-18
PID Error Flags	.8-18
Establishing the Loop Table Size and Location	.8-18
Loop Table Word Definitions	.8-20
PID Mode Setting 1 Bit Descriptions (Addr + 00)	.8-21
PID Mode Setting 2 Bit Descriptions (Addr + 01)	.8-22
Mode/Alarm Monitoring Word (Addr + 06)	.8-23
Ramp/Soak Table Flags (Addr + 33)	.8-23
Ramp/Soak Table Location (Addr + 34)	.8-24
Ramp/Soak Table Programming Error Flags (Addr + 35)	.8-24
Configure the PID Loop	.8-25
PID Loop Tuning	.8-40
Open-Loop Test	.8-40
Manual Tuning Procedure	.8-41
Alternative Manual Tuning Procedures by Others	.8-44
Tuning PID Controllers	.8-44
Auto Tuning Procedure	.8-45
Use DirectSOFT 5 Data View with PID View	.8-49
Open a New Data View Window	.8-49
Open PID View	.8-50
Using the Special PID Features	.8-53
How to Change Loop Modes	.8-53
Operator Panel Control of PID Modes	.8-54
PLC Modes Effect on Loop Modes	.8-54
Loop Mode Override	.8-54
PV Analog Filter	.8-55
Creating an Analog Filter in Ladder Logic	.8-56

Use the <i>DirectSOFT 5</i> Filter Intelligent Box Instructions	8-57
FilterB Example	8-57
Ramp/Soak Generator	8-58
Introduction	8-58
Ramp/Soak Table	8-59
Ramp/Soak Table Flags	8-61
Ramp/Soak Generator Enable	8-61
Ramp/Soak Controls	8-61
Ramp/Soak Profile Monitoring	8-62
Ramp/Soak Programming Errors	8-62
Testing Your Ramp/Soak Profile	8-62
DirectSOFT 5 Ramp/Soak Example	8-63
Setup the Profile in PID Setup	8-63
Program the Ramp/Soak Control in Relay Ladder	8-63
Test the Profile	8-64
Cascade Control	8-65
Introduction	8-65
Cascaded Loops in the DL06 CPU	8-66
Tuning Cascaded Loops	8-67
Time-Proportioning Control	8-68
On/Off Control Program Example	8-69
Feedforward Control	8-70
Feedforward Example	8-71
PID Example Program	8-72
Program Setup for the PID Loop	8-72
Troubleshooting Tips	8-75
Glossary of PID Loop Terminology	8-77
Bibliography	8-79
Chapter 9: Maintenance and Troubleshooting	
Hardware System Maintenance	9-2
Standard Maintenance	9-2
Diagnostics	9-2
Diagnostics	9-2

Table of Contents

Fatal Errors	9-2
Non-fatal Errors	9-2
V-memory Error Code Locations	9-3
Special Relays (SP) Corresponding to Error Codes	9-3
DL06 Micro PLC Error Codes	9-4
Program Error Codes	9-5
CPU Indicators	9-6
PWR Indicator	9-6
RUN Indicator	9-7
CPU Indicator	9-7
Communications Problems	9-7
I/O Point Troubleshooting	9-8
Possible Causes	9-8
Some Quick Steps	9-8
Handheld Programmer Keystrokes Used to Test an Output Point	9-9
Noise Troubleshooting	9-10
Electrical Noise Problems	9-10
Reducing Electrical Noise	9-10
Machine Startup and Program Troubleshooting	9-11
Syntax Check	9-11
Special Instructions	9-12
Duplicate Reference Check	9-13
Run Time Edits	9-14
Run Time Edit Example	9-15
Forcing I/O Points	9-16
Regular Forcing with Direct Access	9-18
Bit Override Forcing	9-19
Bit Override Indicators	9-19

Chapter 10: LCD Display Panel

Introduction to the DL06 LCD Display Panel	10-2
Keypad	10-2
Snap-in installation	10-3
Display Priority	10-4

Menu Navigation	10-5
Confirm PLC Type, Firmware Revision Level, Memory Usage, Etc.	10-6
Examining Option Slot Contents	10-8
Menu 2, M2:SYSTEM CFG.	10-8
Monitoring and Changing Data Values	10-10
Menu 3, M3:MONITOR	10-10
Data Monitor	10-10
V-memory values	10-10
Pointer values	10-12
Bit Monitor	10-13
Bit status	10-13
Changing Date and Time	10-14
Menu 4, M4 : CALENDAR R/W	10-14
Setting Password and Locking	10-17
Menu 5, M5 : PASSWORD R/W	10-17
Reviewing Error History	10-20
Menu 6, M6 : ERR HISTORY	10-20
Toggle Light and Beeper, Test Keys	10-21
Menu 7, M7 : LCD TEST&SET	10-21
PLC Memory Information for the LCD Display Panel	10-22
Data Format Suffixes for Embedded V-memory Data	10-22
Reserved memory registers for the LCD Display Panel	10-23
V7742 bit definitions	10-24
Changing the Default Screen	10-25
Example program for setting the default screen message	10-25
DL06 LCD Display Panel Instruction (LCD)	10-26
Source of message	10-26
ASCII Character Codes	10-27
Example program: alarm with embedded date/time stamp	10-28
Example program: alarm with embedded V-memory data	10-29
Example program: alarm text from V-memory with embedded V-memory data ..	10-30
 Appendix A: Auxiliary Functions	
Introduction	A-2

Table of Contents

Purpose of Auxiliary Functions	A-2
Accessing AUX Functions via DirectSOFT 5	A-3
Accessing AUX Functions via the Handheld Programmer	A-3
AUX 2* — RLL Operations	A-4
AUX 21 Check Program	A-4
AUX 22 Change Reference	A-4
AUX 23 Clear Ladder Range	A-4
AUX 24 Clear Ladders	A-4
AUX 3* — V-memory Operations	A-4
AUX 31 Clear V-memory	A-4
AUX 4* — I/O Configuration	A-5
AUX 41 Show I/O Configuration	A-5
AUX 5* — CPU Configuration	A-5
AUX 51 Modify Program Name	A-5
AUX 53 Display Scan Time	A-5
AUX 54 Initialize Scratchpad	A-5
AUX 55 Set Watchdog Timer	A-5
AUX 56 CPU Network Address	A-6
AUX 57 Set Retentive Ranges	A-6
AUX 58 Test Operations	A-6
AUX 59 Bit Override	A-7
AUX 5B Counter Interface Configuration	A-7
AUX 5D Select PLC Scan Mode	A-7
AUX 6* — Handheld Programmer Configuration	A-8
AUX 61 Show Revision Numbers	A-8
AUX 62 Beeper On/Off	A-8
AUX 65 Run Self Diagnostics	A-8
AUX 7* — EEPROM Operations	A-8
Transferrable Memory Areas	A-8
AUX 71 CPU to HPP EEPROM	A-8
AUX 72 HPP EEPROM to CPU	A-9
AUX 73 Compare HPP EEPROM to CPU	A-9
AUX 74 HPP EEPROM Blank Check	A-9
AUX 75 Erase HPP EEPROM	A-9
AUX 76 Show EEPROM Type	A-9

AUX 8* — Password OperationsA-9

 AUX 81 Modify PasswordA-9

 AUX 82 Unlock CPUA-10

 AUX 83 Lock CPUA-10

Appenedix B: DL06 Error codes

DL06 Error CodesB-2

Appendix C: Instruction Execution Times

IntroductionC-2

 V-Memory Data RegistersC-2

 V-Memory Bit RegistersC-2

 How to Read the TablesC-2

Instruction Execution TimesC-3

 Boolean InstructionsC-3

 Comparative Boolean InstructionsC-4

 Immediate InstructionsC-11

 Bit of Word Boolean InstructionsC-12

 Timer, Counter and Shift RegisterC-13

 Accumulator Data InstructionsC-14

 Logical InstructionsC-15

 Math InstructionsC-16

 Differential InstructionsC-19

 Bit InstructionsC-19

 Number Conversion InstructionsC-20

 Table InstructionsC-20

 CPU Control InstructionsC-22

 Program Control InstructionsC-22

 Interrupt InstructionsC-22

 Network InstructionsC-22

 Intelligent I/O InstructionsC-23

 Message InstructionsC-23

 RLLplus InstructionsC-23

 Drum InstructionsC-23

 Clock / Calender InstructionsC-24

 MODBUS InstructionsC-24

Table of Contents

ASCII Instructions	C-24
--------------------------	------

Appendix D: Special Relays

DL06 PLC Special Relays	D-2
Startup and Real-Time Relays	D-2
CPU Status Relays	D-2
System Monitoring	D-3
Accumulator Status	D-3
HSIO Input Status	D-4
HSIO Pulse Output Relay	D-4
Communication Monitoring Relay	D-4
Option Slot Communication Monitoring Relay	D-4
Option Slot Special Relay	D-4
Counter 1 Mode 10 Equal Relays	D-5
Counter 2 Mode 10 Equal Relays	D-6

Appendix E: High-speed Input and Pulse Output Features

Introduction	E-2
Built-in Motion Control Solution	E-2
Availability of HSIO Features	E-2
Dedicated High-Speed I/O Circuit	E-3
Wiring Diagrams for Each HSIO Mode	E-3
Choosing the HSIO Operating Mode	E-4
Understanding the Six Modes	E-4
Default Mode	E-5
Configuring the HSIO Mode	E-6
Configuring Inputs X0 – X3	E-6
Mode 10: High-Speed Counter	E-7
Purpose	E-7
Functional Block Diagram	E-7
Wiring Diagram	E-8
Interfacing to Counter Inputs	E-8
Setup for Mode 10	E-9
Presets and Special Relays	E-9
Absolute and Incremental Presets	E-10
Preset Data Starting Location	E-11
Using Fewer than 24 Presets	E-11

Equal Relay Numbers	E-12
Calculating Your Preset Values	E-13
X Input Configuration	E-14
Writing Your Control Program	E-15
Program Example 1: Counter Without Presets	E-16
Program Example 2: Counter With Presets	E-18
Program Example 3: Counter With Preload	E-21
Troubleshooting Guide for Mode 10	E-23
Symptom: The counter does not count.	E-23
Symptom: The counter counts but the presets do not function.	E-23
Symptom: The counter counts up but will not reset.	E-23
Mode 20: Up/Down Counter	E-24
Purpose	E-24
Functional Block Diagram	E-24
Quadrature Encoder Signals	E-25
Wiring Diagram	E-25
Interfacing to Encoder Outputs	E-26
Setup for Mode 20	E-27
Preset and Special Relays	E-27
X Input Configuration	E-28
Mode 20 Up/Down Counter	E-28
Writing Your Control Program	E-29
Program Example 1: Quadrature Counting with an Interrupt	E-30
Program Example 2: Up/Down Counting with Standard Inputs	E-32
Program Example 3: Quadrature Counting	E-34
Troubleshooting Guide for Mode 20	E-37
Symptom: The counter does not count.	E-37
Symptom: The counter counts in the wrong direction	E-37
Symptom: The counter counts up and down but will not reset.	E-37
Mode 30: Pulse Output	E-38
Purpose	E-38
Functional Block Diagram	E-39
Wiring Diagram	E-40
Interfacing to Drive Inputs	E-40
Motion Profile Specifications	E-41
Physical I/O Configuration	E-41
Logical I/O Functions	E-41

Table of Contents

Setup for Mode 30	E-42
Profile / Velocity Select Register	E-43
Profile Parameter Table	E-43
Automatic Trapezoidal Profile	E-43
Step Trapezoidal Profile	E-44
Velocity Control	E-44
Step Trapezoidal Profile	E-44
Choosing the Profile Type	E-45
Automatic Trapezoidal Profile Defined	E-45
Step Trapezoidal Profiles Defined	E-46
Velocity Control Defined	E-46
Automatic Trapezoidal Profile Operation	E-47
Program Example 1: Automatic Trapezoidal Profile without External Interrupt	E-48
Preload Position Value	E-49
Program Example 2: Automatic Trapezoidal Profile with External Interrupt	E-50
Program Example 3: Automatic Trapezoidal Profile with Home Search	E-53
Step Trapezoidal Profile Operation	E-55
Program Example 4: Step Trapezoidal Profile	E-56
Velocity Profile Operation	E-59
Program Example 5: Velocity Profile	E-60
Automatic Trapezoidal Profile Error Codes	E-62
Troubleshooting Guide for Mode 30	E-62
Symptom: The stepper motor does not rotate.	E-62
Symptom: The motor turns in the wrong direction.	E-63
Mode 40: High-Speed Interrupts	E-64
Purpose	E-64
Functional Block Diagram	E-64
Setup for Mode 40	E-65
Interrupts and the Ladder Program	E-65
External Interrupt Timing Parameters	E-66
Timed Interrupt Parameters	E-66
X Input / Timed INT Configuration	E-66
Program Example 1: External Interrupt	E-67
Program Example 2: Timed Interrupt	E-68
Mode 50: Pulse Catch Input	E-69
Purpose	E-69
Functional Block Diagram	E-69

Pulse Catch Timing Parameters	E-69
Setup for Mode 50	E-70
X Input Configuration	E-71
Program Example 1: Pulse Catch	E-72
Mode 60: Discrete Inputs with Filter	E-73
Purpose	E-73
Functional Block Diagram	E-73
Input Filter Timing Parameters	E-73
Setup for Mode 60	E-74
X Input Configuration	E-74
Program Example: Filtered Inputs	E-75
 Appendix F: PLC Memory	
DL06 PLC Memory	F-2
Non-volatile V-memory in the DL06	F-3
 Appendix G: ASCII Table	
ASCII Conversion Table	G-2
 Appendix H: Product Weights	
Product Weight Table	H-2
 Appendix I: Numbering Systems	
Introduction	I-2
Binary Numbering System	I-2
Hexadecimal Numbering System	I-3
Octal Numbering System	I-4
Binary Coded Decimal (BCD) Numbering System	I-5
Real (Floating Point) Numbering System	I-5
BCD/Binary/Decimal/Hex/Octal -What is the Difference?	I-6
Data Type Mismatch	I-7
Signed vs. Unsigned Integers	I-8
AutomationDirect.com Products and Data Types	I-9

Table of Contents

<i>Direct</i> LOGIC PLCs	I-9
C-more/C-more Micro-Graphic Panels	I-9

Appendix J: European Union Directives (CE)

European Union (EU) Directives	J-2
Member Countries	J-2
Applicable Directives	J-2
Compliance	J-2
General Safety	J-3
Special Installation Manual	J-4
Other Sources of Information	J-4
Basic EMC Installation Guidelines	J-4
Enclosures	J-4
AC Mains Filters	J-5
Suppression and Fusing	J-5
Internal Enclosure Grounding	J-5
Equi-potential Grounding	J-6
Communications and Shielded Cables	J-6
Analog and RS232 Cables	J-7
Multidrop Cables	J-7
Shielded Cables within Enclosures	J-7
Analog Modules and RF Interference	J-7
Network Isolation	J-8
DC Powered Versions	J-8
Items Specific to the DL06	J-9

Appendix K: Introduction to Serial Communications

Introduction to Serial Communications	K-2
Wiring Standards	K-2
Communications Protocols	K-3
DL06 Port Specifications	K-5
DL06 Port Pinouts	K-5
Port Setup Using DirectSOFT 5 or Ladder Logic Instructions	K-6
Port 2 Setup for RLL Using K-Sequence, DirectNET or MODBUS RTU	K-7
K-Sequence Communications	K-10
DirectNET Communications	K-10

Step 1: Identify Master Port # and Slave #K-10
Step 2: Load Number of Bytes to TransferK-10
Step 3: Specify Master Memory AreaK-11
Step 4: Specify Slave Memory AreaK-12
Communications from a Ladder ProgramK-13
Multiple Read and Write InterlocksK-13
MODBUS RTU CommunicationsK-14
ASCII CommunicationsK-14

Index