

# BRAKING COMPONENT CONFIGURATION AND WIRING

# TABLE OF CONTENTS

Operational Electrical Information
Overload Relay
Dynamic Braking Unit Setup
DBU Jumper and Wiring Terminal Locations
DBU Voltage Jumper Settings
DBU Master/Slave Jumper Settings
Dynamic Braking Wiring
Wiring Warnings and Notes
Maximum Wiring Distances
Dynamic Braking Unit Wiring Terminals
Basic Braking Wiring Diagram 3–9
Specific Braking Wiring Diagrams

# **OPERATIONAL ELECTRICAL INFORMATION**

The *DURAPULSE* AC Drive and Dynamic Braking Unit will both be energized at the same time when power is applied to the drive. (Please refer to the applicable *DURAPULSE* AC Drive User Manual (GS3\_UMW or GS4\_UMW) to determine the start and stop operation of the motor.) The Dynamic Braking Unit will monitor the internal DC bus voltage of the AC drive. When the AC drive stops the motor by decelerating, the braking unit will detect an increase in the drive's DC bus voltage due to the motor causing regeneration. The braking unit will then dissipate this excess energy into the braking resistor in the form of heat. Dissipating this regenerated energy will allow a stable and controlled deceleration of the motor.

The alarm relay output contact terminals (RC, RA, & RB) of the dynamic braking unit will be activated when the temperature of the braking unit heat sink exceeds 203°F (95°C) for DBUs  $\leq$  100hp, or 176°F (80°C) for DBUs > 100hp. This condition can be caused by the ambient temperature surrounding the braking unit exceeding 50°C (122°F), or by the Duty Cycle exceeding 10%. If this high ambient temperature situation exists, then a method of reducing the ambient temperature by the use of forced air cooling or some other means should be considered.

If the resistor does not have a temperature switch, install an overload relay between the DBU and the resistor.

# **OVERLOAD RELAY**

For safety purposes, install an external overload relay between the dynamic braking unit and the braking resistor. Wire the overload relay normally closed contact in series with the coil of a magnetic contactor to interrupt the power to the AC drive.

The purpose of installing the thermal overload relay is to protect the braking resistor from damage due to frequent braking, or due to the braking unit operating excessively due to unusually high input voltage.

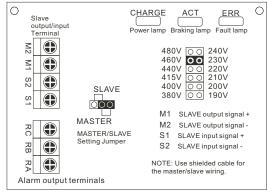


For overload relay selection information, refer to "Overload Relay Selection" in Chapter 1, page <u>1-5</u>.

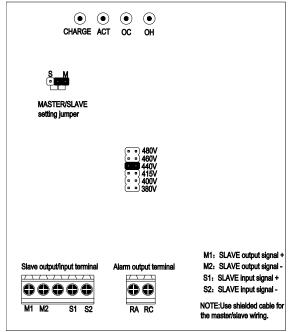
# **DYNAMIC BRAKING UNIT SETUP**

#### DBU JUMPER AND WIRING TERMINAL LOCATIONS

#### DBU ≤ 100hp (GS-1DBU, GS-2DBU, GS-3DBU, GS-4DBU)



#### DBU > 100hp (GS-5DBU, GS-6DBU, GS-7DBU)



#### DBU VOLTAGE JUMPER SETTINGS

The power source for the *DURAPULSE* dynamic braking unit is DC bus voltage from the +(P) and -(N) terminals of the GS drive. It is important to set the voltage selection jumper of the *DURAPULSE* dynamic braking unit accurately based on the input power of the GS drive before operation. The voltage selection jumper setting determines the GS DC bus voltage level at which dynamic braking is applied.



Before setting the voltage selection jumper, make sure the power has been turned off. Set the jumper to match the highest possible voltage for an unstable power system.

Example: A 380VAC power system rises to 410VAC on a regular basis. To avoid engaging dynamic braking when the power supply voltage rises above 380VAC, set the voltage selection jumper to the 415VAC position.



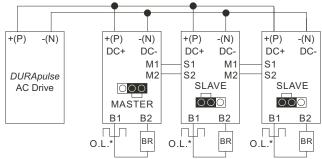
For DURApulse AC drives, set the "Over Voltage Stall Prevention" parameter as "close (1)" to disable over-voltage stall prevention (P6.05 in GS3; P6.11 in GS4). This will ensure a stable deceleration characteristic.

	BRAKING UNIT VOLTAGE SETTINGS												
	MODELS		MODELS > 100HP										
	(GS-1DBU, GS-2DBU	ļ	(GS-5DBU,	GS-6DBU, GS-7DBU)									
23	OVAC CLASS		4	60VAC CLASS									
AC Power Voltage	BRAKING START-UP VOLTAGE DC BUS (+(P), -(N)) VOLTAGE	AC Power Voltage	BRAKING START-UP VOLTAGE DC BUS (+(P), -(N)) VOLTAGE		AC Power Voltage	BRAKING START-UP VOLTAGE DC BUS (DC+,DC-) VOLTAGE							
190 VAC	330 VDC	380 VAC	660 VDC		380 VAC	618 VDC							
200 VAC	345 VDC	400 VAC	690 VDC		400 VAC	642 VDC							
210 VAC	360 VDC	415 VAC	720 VDC		415 VAC	667 VDC							
220 VAC	220 VAC 380 VDC 440 VAC 760 VDC 440 VAC 690 VDC												
230 VAC	230 VAC 400 VDC 460 VAC 800 VDC 460 VAC 725 VDC												
240 VAC	415 VDC	480 VAC	830 VDC		480 VAC	750 VDC							
NOTE: Input Power With Tolerance ±10%													

# DBU MASTER/SLAVE JUMPER SETTINGS

The MASTER/SLAVE jumper on the *DURAPULSE* dynamic braking unit has a factory default setting as a MASTER. If the application of the *DURAPULSE* AC drive requires the use of more than one DBU, then the power terminals of the multiple units are wired in parallel and the first unit is set to MASTER while all remaining units are set to SLAVE. The jumper settings along with the wiring between the MASTER/SLAVE (M1, M2, S1 & S2) terminals allows the multiple braking units to synchronize the power dissipation between braking units. This assures each unit is dissipating an equivalent amount of energy to allow rapid deceleration of the motor.

Typical one-line wiring diagram for multiple parallel DURAPULSE dynamic braking units. The first DBU has the jumper set to MASTER, while the remaining DBUs are set to SLAVE. (DBU  $\leq$  100hp have terminals +(P) & -(N); DBU > 100hp have terminals DC+ & DC-)



\* Although it is recommended, the use of a thermal overload relay in line with the braking resistor is not required. GS-xxxx-BR-ENC braking resistors include a thermostat for thermal protection of the braking resistor, and are the preferred method of protection when available. Orient the braking resistors such that the thermostat is above the resistors in the enclosure, as this will ensure that the thermostat is exposed to the rising air temperature produced by the resistors. Refer to the "Basic Braking Wiring Diagram" on page <u>3–9</u> for details.

# **DYNAMIC BRAKING WIRING**

#### WIRING WARNINGS AND NOTES



Do not proceed with any wiring while power is applied to the circuit, or while the drive or DBU charge LED(s) are on.



To prevent personal injury, do not connect/disconnect wires or regulate the setting of the braking unit while power on. Do not touch the terminals of related wiring and any component on PCB lest users be injured by extremely dangerous DC high voltage.



CONFIRM THAT THE +(P) AND -(N) TERMINALS OF THE DURAPULSE AC DRIVE ARE PROPERLY CONNECTED TO THE DURAPULSE DYNAMIC BRAKING UNIT WITH THE CORRECT POLARITY BEFORE APPLYING POWER. OTHERWISE, THE DRIVE AND THE BRAKING UNIT COULD BE DAMAGED.



Connect the braking unit ground terminal to Earth Ground. The ground lead must be the same gauge wire or larger than leads +(P) and -(N) or DC+ and DC-.



DO NOT WIRE TERMINALS -(N) OR DC- TO THE NEUTRAL POINT OF THE POWER SYSTEM.



DURING BRAKING, THE WIRES CONNECTED TO +(P), -(N),  $DC_+$ ,  $DC_-$ , B1, and B2 generate powerful electromagnetic fields due to high current passing through. Separate these wires from other low voltage control circuits to prevent electrical interference or improper operation.



Before wiring the resistor(s) to the dynamic braking unit(s), check the min. resistor values shown in the Braking Component Selection tables in Ch.1 of this user manual, and make sure the actual resistance is no less than this value. Damage to the dynamic braking unit and/or resistors and other equipment can result if the wrong resistance value is used.



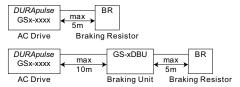
For safety purposes, install an overload relay between the dynamic braking unit and the braking resistor. Wire the overload relay normally closed contact in series with the coil of a magnetic contactor to interrupt the power to the AC drive to prevent damage to the braking resistor in the case of excessive braking or unusually high input voltage.

#### MAXIMUM WIRING DISTANCES



Wire sizes and wiring distances must comply with applicable electrical codes.

- From DURAPULSE AC Drive (GSx-xxxx) to Braking Resistor (GS-BR-xxxxxxx): 5m [16ft]
- From DURAPULSE AC Drive (GSx-xxxx) to DURAPULSE Dynamic Braking Unit (GS-xDBU): 10m [33ft]
- From DURAPULSE Dynamic Braking Unit (GS-xDBU) to Braking Resistor (GS-BR-xxxxxx): 5m [16ft]



#### **DYNAMIC BRAKING UNIT WIRING TERMINALS**



Wire sizes and wiring distances must comply with applicable electrical codes.



Ring terminals are recommended to be used for main circuit wiring. Make sure the terminals are fastened before power is applied.

#### **Ring Terminals**

Ring terminals are not required by UL, but they can be used according to the UL conditions of acceptability.

#### **UL Conditions of Acceptability**

For use only in Industrial Control Equipment where the acceptability is determined by Underwriters Laboratories Inc.

This component controller has been judged on the basis of the required spacings in the Standard for Power Conversion Equipment, UL 508C, Pollution Degree 2.

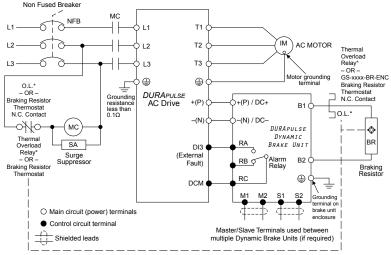
The following shall be considered in the final application:

- 1) Terminals are acceptable for factory or field wiring.
- 2) Device shall be installed in a suitable enclosure.
- Failure mode testing of the voltage sensing circuit, which could result in operation of the DC bus input at transient voltages higher than 800VDC during motor regeneration, was not performed.
- 4) These devices should be mounted and used according to the manufacturer's directions and specifications with regard to compatibility with drive type (see Ratings Section) and braking resistor specification.
- 5) The manufacturer should provide in the end product all literature designating use of the devices as described in Condition of Acceptability 4) above.
- 6) Temperature testing was performed in a 150% outer enclosure and results found acceptable for use in 25°C ambient outside of the 150% outer enclosure. Use at elevated ambients with other enclosure configurations will require heat testing with the actual intended enclosure and the elevated ambient.

BRAKING UNIT WIRING TERMINAL SPECIFICATIONS												
BRAKIN	<i>д U</i> NIT МО	DELS: GS-1D	BU, GS-2DBU, GS-3DBU	, GS-4DBU								
CIRCUIT	TERMIN	AL MARK	WIRE SIZE	SCREW	TORQUE							
Power Input Circuit	+(P), -(N)		10–12 AWG [3.5–5.5 mm <sup>2</sup> ]	M4	15.6 in·lb [18 kg·cm]							
Braking Resistor	B1	, B2	10–12 AWG [3.5–5.5 mm <sup>2</sup> ]	M4	15.6 in·lb [18 kg·cm]							
Slave Circuit	Output M1, M2		18–20 AWG [0.8–0.5 mm <sup>2</sup> ]	M2	3 in·lb							
	Input	S1, S2	(with shielded wires)		[4 kg·cm]							
Fault Circuit	RA, I	RB, RC	18–20 AWG [0.8–0.5 mm <sup>2</sup> ]	M2	3 in·lb [4 kg·cm]							
Bi	RAKING UNI	T MODELS: 0	GS-5DBU, GS-6DBU, GS-2	7DBU	[+ KB citi]							
CIRCUIT	TERMIN	AL MARK	WIRE SIZE	SCREW	TORQUE							
Power Input Circuit	DC+	-, DC-	4–6 AWG [21.2–13.3 mm <sup>2</sup> ]	M8	26 in·lb [30 kg·cm]							
Braking Resistor	B1	, B2	4–6 AWG [21.2–13.3 mm <sup>2</sup> ]	M8	26 in·lb [30 kg·cm]							
Slave Circuit	Output	M1, M2	18–20 AWG [0.8–0.5 mm <sup>2</sup> ]	M2	3 in·lb							
Slave Circuit	Input	S1, S2	(with shielded wires)		[4 kg·cm]							
Fault Circuit	ult Circuit RA, RC		18–20 AWG [0.8–0.5 mm <sup>2</sup> ]	M2	3 in·lb [4 kg·cm]							

# DBU Wiring Terminal Specifications

#### BASIC BRAKING WIRING DIAGRAM



\* Although it is recommended, the use of a thermal overload relay in line with the braking resistor is not required. GS-xxxx-BR-ENC braking resistors include a thermostat for thermal protection of the braking resistor, and are the preferred method of protection when available. Orient the braking resistors such that the thermostat is above the resistors in the enclosure, as this will ensure that the thermostat is exposed to the rising air temperature produced by the resistors.



Smaller-capacity DURApulse AC Drives can connect directly to braking resistors, and do not require Dynamic Braking Units for braking. Refer to the "Dynamic Braking Component Selection" section of Chapter 1 to determine which braking components are required for each drive.

Although it is recommended, the use of a thermal overload relay in line with the braking resistor is not required. GS-xxxx-BR-ENC braking resistors include a thermostat for thermal protection of the braking resistor, and are the preferred method of protection when available. Orient the braking resistors such that the thermostat is above the resistors in the enclosure, as this will ensure that the thermostat is exposed to the rising air temperature produced by the resistors.



For overload relay information, Refer to the "Overload Relay" section at the beginning of this chapter.

# SPECIFIC BRAKING WIRING DIAGRAMS

Wiring Diagram Index for GS3 Drives

	GS <u>3</u> AC Drive Braking Wiring Diagram Index														
	230	VAC Dr.	IVE	AND MC	то	r Voltage			460	VAC DR	IVE	AND MO	то	r Voltage	
Mo Pov		AC Drive		RAKING UNIT		BRAKING RESISTOR	DIAGRAM		TOR WER	AC Drive		RAKING UNIT		BRAKING RESISTOR	DIAGRAM
(нр)	(ĸW)	Part # GS3-	QUANTITY	PART # GS-	QUANTITY	PART #		(нр)	(ĸW)	Part # GS3-	QUANTITY	PART # GS-	QUANTITY	PART # GS-	WIRING DIA
1	0.7	21P0			1	21P0-BR	П	1	0.7	41P0			1	41P0-BR	
2	1.5	22P0			1	22P0-BR		2	1.5	42P0	]		1	42P0-BR	
3	2.2	23P0			1	23P0-BR		3	2.2	43P0			1	43P0-BR	
5	3.7	25P0	0	n/a	1	25P0-BR	A	5	3.7	45P0	0	n/a	1	45P0-BR	Α
7.5	5.5	27P5			1	27P5-BR		7.5	5.5	47P5			1	47P5-BR	
10	7.5	2010			1	2010-BR-ENC		10	7.5	4010			1	4010-BR	
15	11	2015			1	2015-BR-ENC		15	11	4015			1	4015-BR-ENC	
20	15	2020	1	2DBU	1	2020-BR-ENC		20	15	4020	1	4DBU	1	4020-BR-ENC	
25	18	2025	1	2DBU	1	2025-BR-ENC	D	25	18	4025	1	4DBU	1	4025-BR-ENC	
30	22	2030	1	2DBU	1	2030-BR-ENC		30	22	4030	1	4DBU	1	4030-BR-ENC	Ы
40	30	2040	2	2DBU	2	2040-BR-ENC	F	40	30	4040	1	4DBU	1	4040-BR-ENC	
50	37	2050	2	2DBU	2	2050-BR-ENC	Ľ	50	40	4050	1	4DBU	1	4050-BR-ENC	
								60	45	4060	1	4DBU	1	4060-BR-ENC	
								75	55	4075	2	4DBU	2	4075-BR-ENC	F
								100	75	4100	2	4DBU	2	4100-BR-ENC	<b>'</b>

# Wiring Diagram Index for GS4 Drives

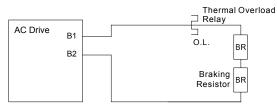
	GS <u>4</u> AC Drive Braking Wiring Diagram Index														
	230	VAC Dri	VE /	AND MOT	OR	VOLTAGE			460	VAC Dri	VE /	AND MO	OR V	OLTAGE	
Мо	TOR		В	RAKING		BRAKING		Мо	TOR		B	RAKING	E	BRAKING	
PO	WER	AC		UNIT		RESISTOR		PO	NER	AC		UNIT	F		
(нр)	(ĸW)	DRIVE PART # GS4-	QUANTITY	PART # GS-	QUANTITY	PART # GS-BR-	DIAGRAM #	(нр)	(ĸW)	Drive Part # GS4-	QUANTITY	PART # GS-	QUANTITY	PART # GS-BR-	DIAGRAM #
1	0.7	21P0			1	080W200		1	0.7	41P0			1	080W750	
2	1.5	22P0			1	200W091		2	1.5	42P0			1	200W360	
3	2.2	23P0			1	300W070		3	2.2	43P0			1	300W250	
5	3.7	25P0			1	400W040	A	5	3.7	45P0			1	400W150	A
7.5	5.5	27P5	0	n/a	1	1K0W020		7.5	5.5	47P5			1	1K0W075	
10	7.5	2010		11/a	1	1K0W020		10	7.5	4010	0	n/a	1	1K0W075	
15	11	2015			1	1K5W013		15	11	4015			1	1K5W043	
20	15	2020			2	1K0W4P3		20	15	4020			2	1K0W016	
25	18	2025			2	1K0W4P3	В	25	18	4025			2	1K0W016	В
30	22	2030			2	1K5W3P3		30	22	4030			2	1K5W013	
40	30	2040	2	1DBU	4	1K0W5P1		40	30	4040			4	1K0W016	С
50	37	2050	2	2DBU	4	1K2W3P9	G	50	40	4050	1	4DBU	4	1K2W015	Е
60	45	2060	2	2DBU	4	1K5W3P3		60	45	4060	1	4DBU	4	1K5W013	
75	55	2075	3	2DBU	6	1K2W3P9	J	75	55	4075	2	3DBU	8	1K0W5P1	н
100	75	2100	4	2DBU	8	1K2W3P9	К	100	75	4100	2	4DBU	8	1K2W015	
								125	90	4125	2	4DBU	8	1K5W013	
								150	110	4150	1	5DBU	10	1K2W015	L
								175	132	4175	1	6DBU	12	1K5W012	м
								200	160	4200	1	6DBU	12	1K5W012	
								250	185	4250	1	7DBU	14	1K5W012	N
								300	220	4300	2	5DBU	20	1K2W015	0

		For GS3 230	VAC	C Drives				For GS3 460	VA	C Drives				
AC Drive	B	raking Unit		Braking Resistor	Diag.	AC Drive	Br	aking Unit		Braking Resistor	Diag.			
Part #	#	Part #	#	Part #	Ö	Part #	#	Part #	#	Part #	Ö			
GS3-21P0			1	GS-21PO-BR		GS3-41P0			1	GS-41PO-BR				
GS3-22P0			1	GS-22PO-BR		GS3-42P0			1	GS-42P0-BR				
GS3-23P0			1	GS-23PO-BR		GS3-43P0			1	GS-43P0-BR				
GS3-25P0	0	n/a	1	GS-25PO-BR	A	GS3-45P0	0	n/a	1	GS-45P0-BR	A			
GS3-27P5	]		1	GS-27P5-BR		GS3-47P5			1	GS-47P5-BR				
GS3-2010	ļ		1	GS-2010-BR-ENC		GS3-4010			1	GS-4010-BR				
GS3-2015			1	GS-2015-BR-ENC		GS3-4015			1	GS-4015-BR-ENC				
		For GS4 230	VAC	C Drives			For GS4 460			C Drives				
AC Drive	B	raking Unit		Braking Resistor	ģ	AC Drive	Br	aking Unit		Braking Resistor	ģ			
Part #	#	Part #	#	Part #	Diag.	Part #	#	Part #	#	Part #	Diag.			
GS4-21P0			1	GS-BR-080W200		GS4-41P0			1	GS-BR-080W750				
GS4-22P0	1		1	GS-BR-200W091		GS4-42P0	1		1	GS-BR-200W360	1			
GS4-23P0			n/a	n/a		1	GS-BR-300W070		GS4-43P0			1	GS-BR-300W250	
GS4-25P0	0	n/a	1	GS-BR-400W040	A	GS4-45P0	0	) n/a	1	GS-BR-400W150	A			
GS4-27P5	]		1	GS-BR-1K0W020		GS4-47P5			1	GS-BR-1K0W075	]			
GS4-2010	]		1	GS-BR-1K0W020		GS4-4010	]		1	GS-BR-1K0W075	]			
GS4-2015			1	GS-BR-1K5W013		GS4-4015			1	GS-BR-1K5W043				
				Thermal Overload □ Relay										
AC Drive	ę		Γ											
10 5111	-	B1				0.L.								
		B2	_			Г								
							BR							
						L								
								Braking						
1		Resistor												

#### Wiring Diagram A: [Drive + 1 Resistor]

# Wiring Diagram B: [Drive + 2 Series Resistors]

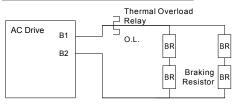
	For GS4 230VAC Drives For GS4 460VAC Drives										
AC Drive	Br	raking Unit		Braking Resistor	iag.	AC Drive	Br	raking Unit		Braking Resistor	ag.
Part #	#	Part #	#	Part #	Ξ	Part #	#	Part #	#	Part #	Ξ
GS4-2020			2	GS-BR-1K0W4P3		GS4-4020			2	GS-BR-1K0W016	
GS4-2025	0	n/a	2	GS-BR-1K0W4P3	в	GS4-4025	0	n/a	2	GS-BR-1K0W016	в
GS4-2030			2	GS-BR-1K5W3P3		GS4-4030			2	GS-BR-1K5W013	



#### DURAPULSE Drives Dynamic Braking User Manual - 2nd Ed., Rev.D - 06/10/2022

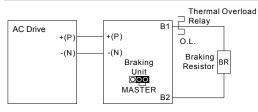
# Wiring Diagram C: [Drive + (2 Series + 2 Parallel) Resistors]

Γ	For GS4 460VAC Drives													
l	AC Drive Braking Unit Braking Resistor													
	Part #	#	Part #	#	Part #	Ö								
L	GS4-4040	0 n/a 4 GS-BR-1K0W01												



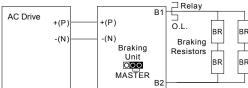
# Wiring Diagram D: [Drive + 1 DBU + 1 Resistor]

	For GS3 230VAC Drives							For GS3 460	VAC	C Drives	
AC Drive	Br	aking Unit		Braking Resistor	а в	AC Drive	Br	aking Unit		Braking Resistor	ы в
Part #	#	Part #	#	Part #	ä	Part #	#	Part #	#	Part #	ö
GS3-2020	1	GS-2DBU	1	GS-2020-BR-ENC		GS3-4020	1	GS-4DBU	1	GS-4020-BR-ENC	
GS3-2025	1	GS-2DBU	1	GS-2025-BR-ENC	D	GS3-4025	1	GS-4DBU	1	GS-4025-BR-ENC	
GS3-2030	1	GS-2DBU	1	GS-2030-BR-ENC		GS3-4030	1	GS-4DBU	1	GS-4030-BR-ENC	D
						GS3-4040	1	GS-4DBU	1	GS-4040-BR-ENC	ש
		n/	а			GS3-4050	1	GS-4DBU	1	GS-4050-BR-ENC	
						GS3-4060	1	GS-4DBU	1	GS-4060-BR-ENC	



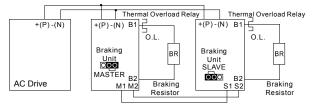
# Wiring Diagram E: [Drive + 1 DBU + (2 Series + 2 Parallel) Resistors]

Γ		For GS4 460VAC Drives													
l	AC Drive	Br	aking Unit		Braking Resistor	Diag.									
	Part #	#	Part #	#	Part #	ö									
	GS4-4050	1	GS-4DBU	4	GS-BR-1K2W015	F									
	GS4-4060	1	GS-4DBU	4	GS-BR-1K5W013	E									
						Th Re	ermal Overload								
	AC Drive				B1 - E		lay								



#### Wiring Diagram F: [Drive + 2 DBUs + 1 Resistor/DBU]

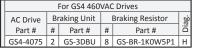
		For GS3 230	VAC	C Drives				For GS3 460	VAC	C Drives	
AC Drive	Br	aking Unit		Braking Resistor	ав.	AC Drive	B	aking Unit		Braking Resistor	ė
Part #	#	Part #	#	Part #	ö	Part #	#	Part #	#	Part #	Dia
GS3-2040	2	GS-2DBU	2	GS-2040-BR-ENC	_	GS3-4075	2	GS-4DBU	2	GS-4075-BR-ENC	-
GS3-2050	2	GS-2DBU	2	GS-2050-BR-ENC	F	GS3-4100	2	GS-4DBU	2	GS-4100-BR-ENC	F

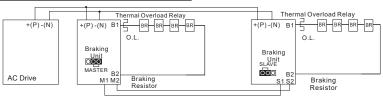


#### Wiring Diagram G: [Drive + 2 DBUs + 2 Series Resistors/DBU]

		For GS4 230		]			
AC Drive	Br	raking Unit		Braking	g Resistor	Diag.	
Part #	#	Part #	#	# Part #			
GS4-2040	2	GS-1DBU	4 GS-BR-1K0W5P1				
GS4-2050	2	GS-2DBU	4	GS-BF	R-1K2W3P9	G	
GS4-2060	2	GS-2DBU	4	GS-BF	R-1K5W3P3		
+(P	, ,		(P) - Brak Ur OOT	(N) B1 king hit	O.L. BR BR Braking Resistor		ay Thermal Overload Relay +(P)-(N) B1 O.L. BR Braking Unit SLAVE S1 S2 Braking Resistor

#### H: [Drive + 2 DBUs + 4 Series Resistors/DBU]

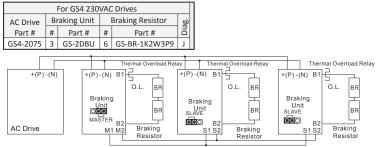




#### Wiring Diagram I: [Drive + 2 DBUs + (2 Series + 2 Parallel) Resistors/DBU]

	ng biagia		in [Dirite .	-	BBBB - (E Berne	· ·	2 Turunen, nesistors, b
Γ			For GS4 460	VAC	C Drives		
	AC Drive	Br	aking Unit		Braking Resistor	iag.	
	Part #	#	Part #	#	Part #	ä	
	GS4-4100	2	GS-4DBU	8	GS-BR-1K2W015		
L	GS4-4125	2	GS-4DBU	8	GS-BR-1K5W013	1	
	+(P) -	(N)	Br	akir Jnit OO	BR BR		Thermal Overload Relay +(P)-(N) B1 O.L. BR BR Unit SLAVE S1 S2 Braking COO B2 S1 S2 Braking Resistor

#### Wiring Diagram J: [Drive + 3 DBUs + 2 Series Resistors/DBU]

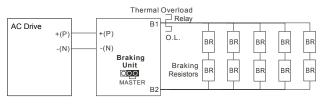


# Wiring Diagram K: [Drive + 4 DBUs + 2 Series Resistors/DBU]

	For GS4 230	VAC Drive	es			
AC Drive	Braking Unit	Brakin	g Resistor	Diag.		
Part #	# Part #	#	Part #	Dig		
GS4-2100 4	4 GS-2DBU	8 GS-B	R-1K2W3P9	К		
+(P)-(N) AC Drive	Therm +(P)-(N) B1 Unit WASTER B2 M1 M2	al Overload Relay O.L. BR BR Braking Resistors	H(P) -(N) B1 Braking Unit SLAVE S1 S2 S1 S2	O.L. BR	Thermal Overload +(P)-(N) B1 Braking Unit SLAVE S1 S2 Braking Resistors	Thermal Overload +(P)-(N) B1 Braking Unit S.V/E S.V/E S.S.Z Braking BR BR BR BR BR BR BR BR BR BR

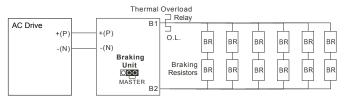
#### Wiring Diagram L: [Drive + 1 DBU + (2 Series + 5 Parallel) Resistors/DBU]

For GS4 460VAC Drives							
AC Drive	Br	aking Unit	Braking Resistor				
Part #	#	Part #	#	Part #	Diag.		
GS4-4150	1	GS-5DBU	10	GS-BR-1K2W015	L		



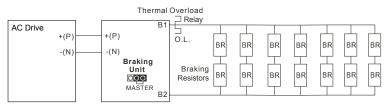
#### Wiring Diagram M: [Drive + 1 DBU + (2 Series + 6 Parallel) Resistors/DBU]

Γ	For GS4 460VAC Drives								
	AC Drive	Br	aking Unit	Braking Resistor		В.			
	Part #	#	Part #	#	Part #	Di			
	GS4-4175	1	GS-6DBU	12	GS-BR-1K5W012				
	GS4-4200	1	GS-6DBU	12	GS-BR-1K5W012	М			



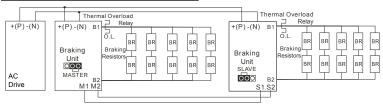
#### Wiring Diagram N: [Drive + 1 DBU + (2 Series + 7 Parallel) Resistors/DBU]

	For GS4 460VAC Drives								
	AC Drive	Br	aking Unit	Braking Resistor					
	Part #	#	Part #	#	Part #	]ä			
L	GS4-4250	1	GS-7DBU	14	GS-BR-1K5W012	Ν			



#### Wiring Diagram O: [Drive + 2 DBUs + (2 Series + 5 Parallel) Resistors/DBU]

			-							
Γ	For GS4 460VAC Drives									
	AC Drive	Br	aking Unit	Braking Resistor						
	Part #	#	Part #	#	Part #	Diag.				
	GS4-4300	2	GS-5DBU	20	GS-BR-1K2W015	0				



# BLANK PAGE