AC Servo System Configuration

*Sure*Servo series drives and motors part numbering system

SV A - 2 04 0

Series
SV: *Sure*Servo AC servo

Component Type
A: Drive
L: Low inertia motor
M: Medium inertia motor

Component Option
0: Drive
Blank: Motor without brake
B: Motor with brake

Rated Output Power
01: 100W
02: 200W
04: 400W
07: 750W
10: 1000W
20: 2000W
30: 3000W

Nominal Input Voltage
2: 230VAC; 50/60 Hz

Here is what you will need to order a complete servo system:

NOTE: UNIT CAN BE PROGRAMMED VIA KEYPAD.
OPTIONAL PROGRAMMING SOFTWARE (FREE DOWNLOAD) AND OPTIONAL PROGRAMMING CABLE AVAILABLE.

*Sure*Servo AC servo drive, motor, and cable combinations

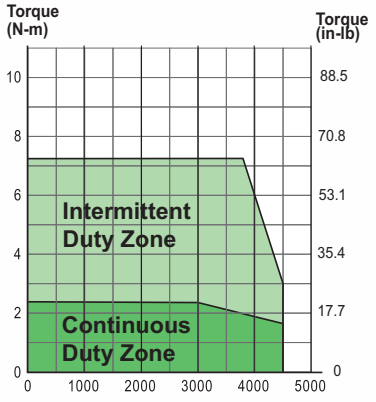
Inertia & Power		Drive and Motor			Power Cables (from Drive to Motor)				Encoder Feedback Cables				Miscellaneous	
Inertia	*Power*	*Servo Drive*	*Servo Motor without brake (note)*	*Servo Motor with brake (note)*	*10 ft*	*20 ft*	*30 ft*	*60 ft*	*10 ft*	*20 ft*	*30 ft*	*60 ft*	*ZIPLink I/O Interface*	*RS-422/485 Serial Communication Cable*
Low inertia	100W	SVA-2040	SVL-201	SVL-201B	SVC-PFL-010	SVC-PFL-020	SVC-PFL-030	SVC-PFL-060	SVC-EFL-010	SVC-EFL-020	SVC-EFL-030	SVC-EFL-060	ZL-RTB50 *and* ZL-SVC-CBL50 or ZL-SVC-CBL50-1 or ZL-SVC-CBL50-2	SVC-MDCOM-CBL
	200W		SVL-202	SVL-202B										
	400W		SVL-204	SVL-204B										
	750W	SVA-2100	SVL-207	SVL-207B										
	1000W		SVL-210	SVL-210B	SVC-PHM-010	SVC-PHM-020	SVC-PHM-030	SVC-PHM-060	SVC-EHH-010	SVC-EHH-020	SVC-EHH-030	SVC-EHH-060		
Medium inertia	1000W		SVM-210	SVM-210B										
	2000W	SVA-2300	SVM-220	SVM-220B	SVC-PHH-010	SVC-PHH-020	SVC-PHH-030	SVC-PHH-060						
	3000W		SVM-230	SVM-230B										

NOTE: EACH SERVO MOTOR REQUIRES AN ENCODER FEEDBACK CABLE AND A POWER CABLE.
THE MOTOR POWER CABLE INCLUDES BRAKE POWER WIRES FOR THE OPTIONAL MOTOR BRAKE.

AC Servo System Configuration

For all systems:
Order programming software & programming cable if needed.
See pgs. 16-27 & 16-28.

750W Low Inertia System



1.

Servo Drive
SVA-2100 <--->

J_m= Motor Inertia = .00096 lb-in-s² (0.000108 kg - m²)

SureServo Motor

2.

SVL-207 <--->
SVL-207B (w/brake) <--->

Motor Power Cable (1)

3.

SVC-PFL-010 (10') <--->
SVC-PFL-020 (20') <--->
SVC-PFL-030 (30') <--->
SVC-PFL-060 (60') <--->

Motor Encoder Cable (1)

4.

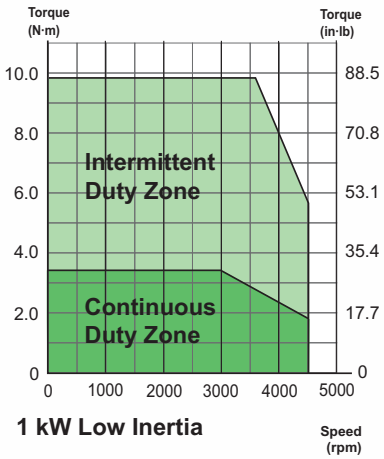
SVC-EFL-010 (10') <--->
SVC-EFL-020 (20') <--->
SVC-EFL-030 (30') <--->
SVC-EFL-060 (60') <--->

*ZIP*Link I/O Interface

5.

ZL-RTB50 <--->
and one cable below:
ZL-SVC-CBL50 (0.5m) <--->
ZL-SVC-CBL50-1 (1m) <--->
ZL-SVC-CBL50-2 (2m) <--->

1 kW Low Inertia System



1.

Servo Drive
SVA-2100 <--->

J_m= Motor Inertia = .0023 lb-in-s² (0.00026 kg - m²)

SureServo Motor

2.

SVL-210 <--->
SVL-210B (w/brake) <--->

Motor Power Cable (1)

3.

SVC-PHM-010 (10') <--->
SVC-PHM-020 (20') <--->
SVC-PHM-030 (30') <--->
SVC-PHM-060 (60') <--->

Motor Encoder Cable (1)

4.

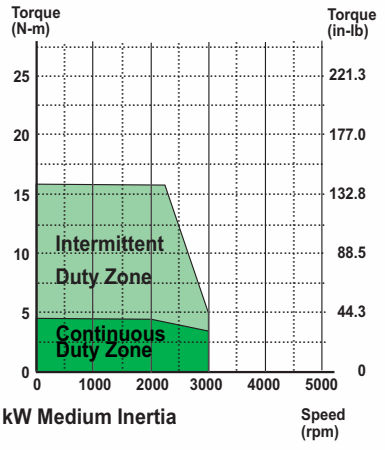
SVC-EHH-010 (10') <--->
SVC-EHH-020 (20') <--->
SVC-EHH-030 (30') <--->
SVC-EHH-060 (60') <--->

*ZIP*Link I/O Interface

5.

ZL-RTB50 <--->
and one cable below:
ZL-SVC-CBL50 (0.5m) <--->
ZL-SVC-CBL50-1 (1m) <--->
ZL-SVC-CBL50-2 (2m) <--->

1 kW Medium Inertia System



1.

Servo Drive
SVA-2100 <--->

J_m= Motor Inertia = .0053 lb-in-s² (0.000598 kg - m²)

SureServo Motor

2.

SVM-210 <--->
SVM-210B (w/brake) <--->

Motor Power Cable (1)

3.

SVC-PHM-010 (10') <--->
SVC-PHM-020 (20') <--->
SVC-PHM-030 (30') <--->
SVC-PHM-060 (60') <--->

Motor Encoder Cable (1)

4.

SVC-EHH-010 (10') <--->
SVC-EHH-020 (20') <--->
SVC-EHH-030 (30') <--->
SVC-EHH-060 (60') <--->

*ZIP*Link I/O Interface

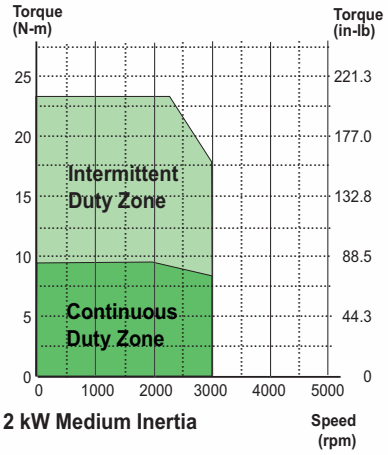
5.

ZL-RTB50 <--->
and one cable below:
ZL-SVC-CBL50 (0.5m) <--->
ZL-SVC-CBL50-1 (1m) <--->
ZL-SVC-CBL50-2 (2m) <--->

AC Servo System Configuration

For all systems:
Order programming software & programming cable if needed. See pgs. 16-27 & 16-28.

2 kW Medium Inertia System



1.

Servo Drive
SVA-2300 <--->

*Sure*Servo Motor

2.

SVM-220 <--->
SVM-220B (w/brake) <--->

Motor Power Cable (1)

3.

SVC-PHH-010 (10') <--->
SVC-PHH-020 (20') <--->
SVC-PHH-030 (30') <--->
SVC-PHH-060 (60') <--->

Motor Encoder Cable (1)

4.

SVC-EHH-010 (10') <--->
SVC-EHH-020 (20') <--->
SVC-EHH-030 (30') <--->
SVC-EHH-060 (60') <--->

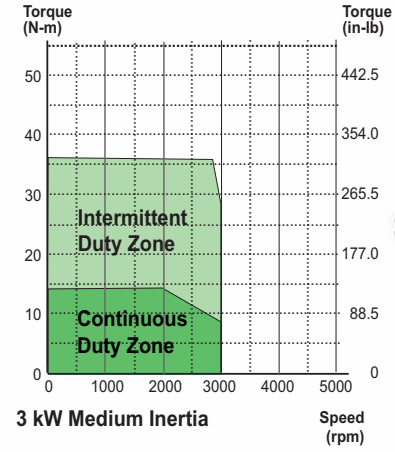
*ZIP*Link I/O Interface

5.

ZL-RTB50 <--->
and one cable below:
ZL-SVC-CBL50 (0.5m) <--->
ZL-SVC-CBL50-1 (1m) <--->
ZL-SVC-CBL50-2 (2m) <--->

J_m= Motor Inertia = .014 lb-in-s^2 = (0.00158 kg - m^2)

3 kW Medium Inertia System



1.

Servo Drive
SVA-2300 <--->

*Sure*Servo Motor

2.

SVM-230 <--->
SVM-230B (w/brake) <--->

Motor Power Cable (1)

3.

SVC-PHH-010 (10') <--->
SVC-PHH-020 (20') <--->
SVC-PHH-030 (30') <--->
SVC-PHH-060 (60') <--->

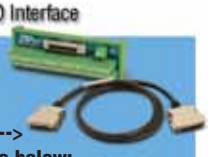
Motor Encoder Cable (1)

4.

SVC-EHH-010 (10') <--->
SVC-EHH-020 (20') <--->
SVC-EHH-030 (30') <--->
SVC-EHH-060 (60') <--->

*ZIP*Link I/O Interface

5.



ZL-RTB50 <--->
and one cable below:
ZL-SVC-CBL50 (0.5m) <--->
ZL-SVC-CBL50-1 (1m) <--->
ZL-SVC-CBL50-2 (2m) <--->

J_m= Motor Inertia = 0.038 lb-in-s^2 = (0.00433 kg - m^2)

NOTE: ALL MOTOR POWER CABLES INCLUDE BRAKE POWER WIRES FOR THE OPTIONAL MOTOR BRAKE.

*Sure*Servo Communications Cables for Muti-drop Networks

Product	Price	Description
SVC-MDCOM-CBL	<--->	RS-422/485 serial communication cable for use with multidrop networks; 3ft length; IEEE 1394 plug to unterminated wires; compatible with all *Sure*Servo systems. Facilitates connection between the *Sure*Servo drive serial port and host controllers.
SVC-232RJ12-CBL-2 *	<--->	*ZIP*Link SureServo Drives cable with 6-pin RJ12 connector to a 6-pin IEEE 1394 connector, shielded, twisted pair, 2.0 meter (6.6 ft.) length. For RS-232 connection to all *Sure*Servo amplifiers.
SVC-485RJ12-CBL-2 *	<--->	*ZIP*Link SureServo amplifier communication cable, RJ12 male to 6-pin IEEE 1394 connector, shielded, twisted pair, 2.0 meter (6.6 ft.) length. Cable used in conjunction with **ZL-CDM-RJ12**xxx distribution module can access a compatible RS-485 device network.
SVC-485HD15-CBL-2 *	<--->	*ZIP*Link SureServo Drives cable with a HD 15-pin male to a 6-pin IEEE 1394 connector, shielded, twisted pair, 2.0 meter (6.6 ft.) length. For RS-485 connection to all *Sure*Servo amplifiers.

**** Refer to the ZIPLinks Wiring Solutions section for complete information regarding the ZIPLink cables.***

AC Servo Drive Specifications

Servo drive overview

Keypad
Five Function keys:

MODE:	Press to select or change mode
NEXT:	Press to shift left
UP:	Press to increase values
DOWN:	Press to decrease values
ENTER:	Press to enter value

LED Display
The LED display has 5 full digits and is used to indicate servo status and alarms

Power On LED
Main power is ON

Control Power Terminal
Single-phase power 230 VAC, 50/60 Hz is connected to L1 and L2

Main Power Terminal
Three-phase power 230 VAC, 50/60 Hz is connected to R, S and T
(Single-phase power 230 VAC 50/60 Hz may be connected to R and S for the low inertia systems)

Motor Output Terminal
The servo motor power cable is connected to U, V and W. Use our factory made and tested cables available in 10, 20, 30 or 60 foot lengths for easy connection.

Regenerative Resistor Terminal
1. When the internal regenerative resistor is used, the P and D terminal are connected together while the P and C connection is left open.
2. When an external regenerative resistor is used, it is connected across the P and C terminals while the P and D connection is left open. Use our factory approved resistors for "sure" results.

Ground Terminals

I/O Interface
50-pin connector for interfacing the host controller (such as *Direct*LOGIC PLC) and other types of I/O signals.

Use our *ZIP*Link kit which provides DIN-rail mounted screw terminals for easy connection.
- Command inputs:
  - Pulse and Direction
  - Encoder Follower
  - Analog Velocity/Torque
- (8) Digital Inputs
- (5) Digital Outputs
- (2) Analog Monitors
- Encoder Output (scalable)
  A+, A-, B+, B-, Z+, Z-

Encoder Interface
20-pin connector for interfacing the servo motor encoder.
Use our factory-made and tested cable available in 10, 20, 30 or 60 foot lengths for easy connection.

Serial Communication Interface
6-pin RS-485/422/232 interface to personal computer with *Sure*Servo Pro set-up software or host controller with Modbus RTU/ASCII protocol. Use our factory-made cables for easy connection to the PC or the host controller.

*Sure*Servo systems run "out-of-the-box"… but may be reconfigured for many applications!

The *Sure*Servo drives are fully digital and include over 165 programmable parameters. For convenience, the parameters are grouped into five categories:

1) Monitor parameters
2) Basic parameters
3) Extended parameters
4) Communication parameters
5) Diagnostic parameters.

All parameters have commonly used default values which allow you to operate the *Sure*Servo system "out-of-the-box". However, the programmability and large variety of parameters make the SureServo systems suitable for a very broad range of applications, including almost all types of general purpose industrial machinery such as assembly, test, packaging, machine tool, and robotics.

SureServo® AC Servo Drive Specifications

Servo drive specifications

General Drive Specifications	
Permissible Frequency	50/60 Hz ±5%
Encoder Resolution / Feedback Resolution	2500 lines / 10000 ppr
Control of Main Circuit	SVPWM (Space Vector Pulse Width Modulation) Control
Tuning Modes	Easy / Auto / Manual
Dynamic Brake	Built-in control
Analog Monitor Outputs (2)	Monitor signal can be set by parameters (Output voltage range: ±8V; Resolution: 12.8 mV/count)
8 Programmable Digital Inputs (45 selectable functions)	Servo enable, Alarm reset, Gain switching, Pulse counter clear, Fault stop, CW/CCW over-travel
	Internal parameter selection, Torque limit activation, Velocity limit activation, Control mode selection
Scalable Encoder Output	Encoder signal output A, /A, B, /B, Z /Z, Line Driver
5 Programmable Outputs (9 selectable indicators)	Servo ready, Servo On, Low velocity, Velocity reached, In Position, Torque limiting, Servo fault, Electromagnetic brake control, Home search completed
Communication Interface	RS-232 / RS-485 / RS-422 / Modbus ASCII & RTU up to 115k Baud
Protective Functions	Overcurrent, Overvoltage, Undervoltage, Overload, Excessive velocity/position error, Encoder error, Regeneration error, Communication error
Installation Site	Indoor location (free from direct sunlight), no corrosive liquid and gas (far away from oil mist, flammable gas, dust)
Altitude	1000m [3281 ft] above sea level – maximum
Operating Temperature	0 to 55 °C [32 to 131 °F] (If operating temperature is above 55°C, forced cooling is required). For long-term reliability, the ambient temperature of *Sure*Servo systems should be under 45°C (113°F).
Storage Temperature	-20° to 65°C (-4° to 149°F)
Humidity	0 to 90% (non-condensing)
Vibration	9.81 m/s^2 (1G) less than 20Hz, 5.88 m/s^2 (0.6G) 20 to 50 Hz
Protection	IP 20
Agency Approvals	CE; UL listed (U.S. and Canada)

AC Servo Drive Specifications

Servo drive specifications (continued)

Model and Mode Specific Drive Specifications										
	AC Servo Model		**SVA-2040**			**SVA-2100**			**SVA-2300**	
	Price		<--->			<--->			<--->	
	Voltage Phase		Single-phase or Three-phase						Three-phase	
	Voltage and Frequency Range		3-phase: 170~255 VAC @ 50/60 Hz ±5%; 1-phase: 200~255 VAC @ 50/60 Hz ±5%						170~255 VAC @ 50/60 Hz ±5%	
	Main Circuit Input Current	**Single Phase**	3.4A @ 400W			8.0A @ 1kW			–	
		Three Phase	2.6A @ 400W			6.2A @ 1kW			13.6A @ 3kW	
	Main Circuit Inrush Current		44A			77A			87A	
	Main Circuit Power Cycling		Maximum 1 power cycle per minute							
	Control Circuit Current and Voltage		43 mA @ 200~255 VAC, 1 phase							
	Control Circuit Inrush Current		32A maximum							
	Cooling System		Natural Air Circulation			Internal Cooling Fan				
	Drive Heat Loss *	**Motor driven ***	SVL-201(B)	SVL-202(B)	SVL-204(B)	SVL-207(B)	SVL-210(B)	SVM-210(B)	SVM-220(B)	SVM-230(B)
		Heat Loss	12W	15W	20W	35W	45W	50W	75W	80W
	Weight		1.5 kg [3.3 lb]			2kg [4lb]			3kg [7lb]	
Position Control Mode	**Max. Input Pulse Frequency**		Max. 500 kpps (Line driver); Max. 200 kpps (Open collector)							
	Pulse Type		Pulse + Direction, A phase + B phase Quadrature, CCW pulse + CW pulse							
	Command Source		External pulse train / Onboard indexer							
	Smoothing Strategy		Low-pass and P-curve filter							
	Electronic Gear		Electronic gear N/M multiple; N: 1~32767, M: 1~32767(1/50<N/M<200)							
	Torque Limit Operation		Set by parameters or by analog input							
	Feed Forward Compensation		Set by parameters							
Velocity Control Mode	**Analog Input Command**	**Voltage Range**	Bipolar ±10 VDC							
		Input Resistance	10 kΩ							
		Time Constant	2.2 µs							
		Resolution	(Varies with input voltage) 13 bits @ 0V~1V; 13~10 bits @ 1V~2V; 10 bits @ 2V~10V							
	Speed Control Range		1:5000							
	Command Source		External analog signal / Onboard indexer							
	Smoothing Strategy		Low-pass and S-curve filter							
	Torque Limit Operation		Set by parameters or via analog input							
	Frequency Response Characteristic		Maximum 450 Hz							
	Speed Accuracy (at rated rotation speed)		0.01% or less at 0 to 100% load fluctuation							
			0.01% or less at ±10% power fluctuation							
			0.01% or less at 0 to 50°C ambient temperature fluctuation							
Torque Control Mode	**Analog Input Command**	**Voltage Range**	Bipolar ±10 VDC							
		Input Resistance	10 kΩ							
		Time Constant	2.2 µs							
		Resolution	10 bits							
	Permissible Time for Overload		8 sec. under 200% rated output							
	Command Source		External analog signal / Onboard indexer							
	Smoothing Strategy		Low-pass filter							
	Speed Limit Operation		Set by parameters or via analog input							

** Drive heat loss varies depending upon which motor is connected to the drive.*

AC Servo Motor Specifications

Servo motor overview

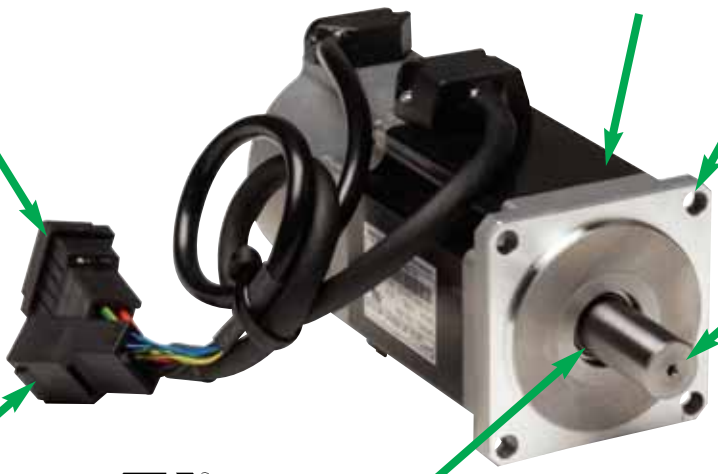
Motor Power and Brake Connector
1-meter cable with 6-position connector (Not liquid tight)

Low Inertia Motors
- 100W 40 mm flange
- 200W 60 mm flange
- 400W 60 mm flange
- 750W 80 mm flange

IP65 Housing

Keyless Shafts
- 100W 8 mm diameter
- 200W 14 mm diameter
- 400W 14 mm diameter
- 750W 19 mm diameter

750W and below



Encoder Connector
1-meter cable with 9-position connector (Not liquid tight)

***Without* Shaft Seal**
(not liquid tight)

All SureServo motors have keyless shafts for use with servo-grade clamp or compression couplings.

Motor Power and Brake Connector
(Liquid tight when using AutomationDirect cables)

Encoder Connector
(Liquid tight when using AutomationDirect cables)

IP65 Housing

1 kW and above

Low and Medium Inertia Motors
Low Inertia Model
- 1 kW 100 mm flange

Medium Inertia Models
- 1 kW 130 mm flange
- 2 kW 180 mm flange
- 3 kW 180 mm flange

Keyless Shafts
Low Inertia Model
- 1 kW 22 mm diameter

Medium Inertia Models
- 1 kW 22 mm diameter
- 2 kW 35 mm diameter
- 3 kW 35 mm diameter

***With* Shaft Seal**
(liquid tight)

AC Servo Motor Specifications

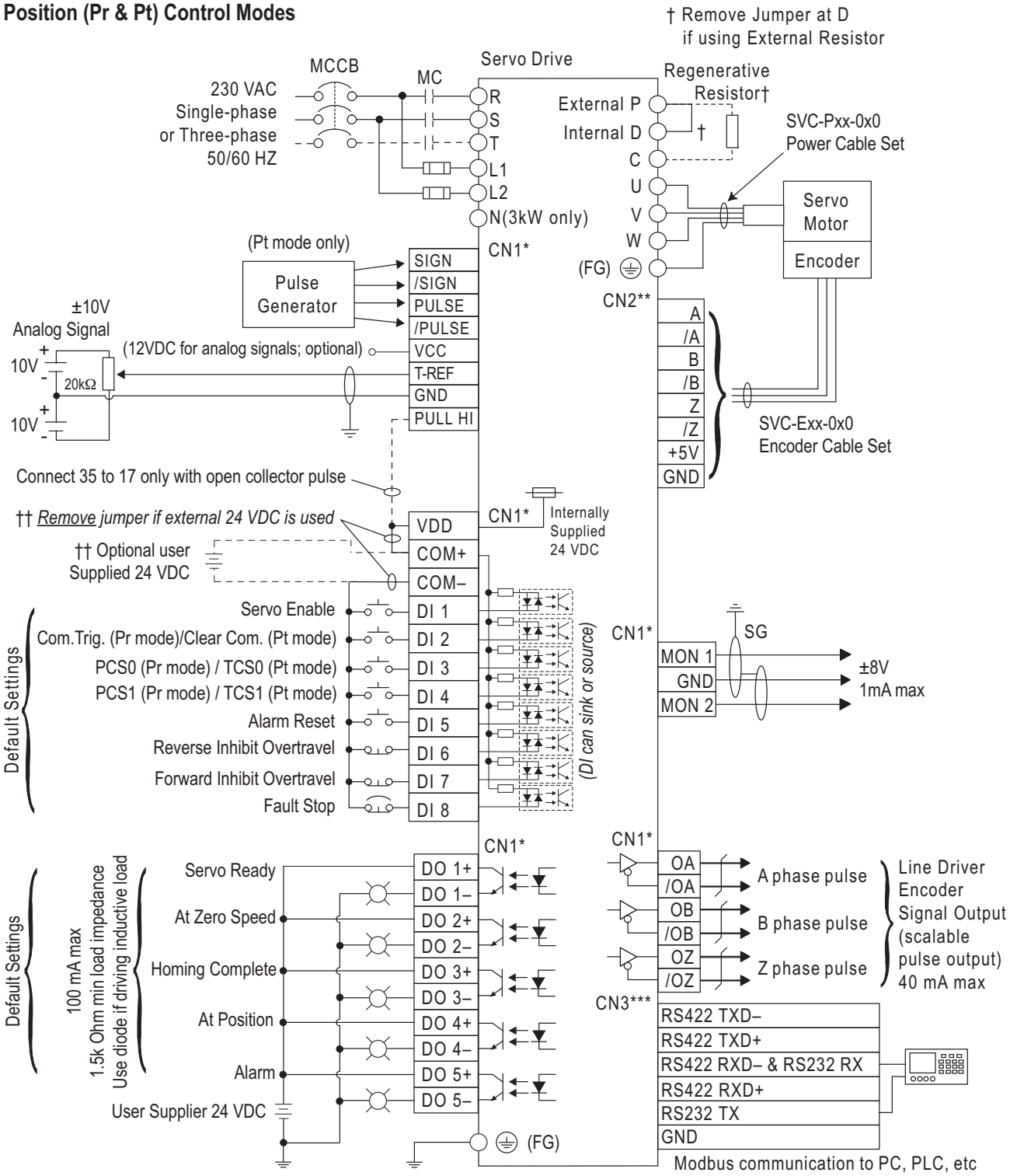
Motor Specifications										
Inertia Range			Low					Medium		
Model Name: Sxx-xxx			SVL-201	SVL-202	SVL-204	SVL-207	SVL-210	SVM-210	SVM-220	SVM-230
Price			<--->	<--->	<--->	<--->	<--->	<--->	<--->	<--->
Model with brake: Sxx-xxxB			SVL-201B	SVL-202B	SVL-204B	SVL-207B	SVL-210B	SVM-210B	SVM-220B	SVM-230B
Price			<--->	<--->	<--->	<--->	<--->	<--->	<--->	<--->
Rated output power		W	100	200	400	750	1000	1000	2000	3000
Rated torque		N-m	0.318	0.64	1.27	2.39	3.3	4.8	9.4	14.3
		lb-in	2.8	5.7	11.2	21.2	29.2	42.5	83.2	125.7
Maximum torque		N-m	0.95	1.91	3.82	7.16	9.9	15.7	23.5	35.8
		lb-in	8.4	16.9	33.8	63.4	87.6	138.9	208.0	316.8
Rated speed		rpm	3000					2000		
Max. speed		rpm	5000			4500		3000		
Rated current		A	1.1	1.7	3.3	5.0	6.8	5.6	13.1	17.4
Max. current		A	3.0	4.9	9.3	14.1	18.7	17.6	31.4	42.3
Drive input current		1 phase A	1.0	1.7	3.4	5.9	8.0	8.0	-	-
		3 phase A	0.8	1.3	2.6	4.7	6.2	6.2	9.1	13.6
Max. radial shaft load		N	78.4	196		343	490	784		
		lb	18	44		77	110	176		
Max. thrust shaft load		N	39.2	68.6		98		392		
		lb	9	15		22		88		
Brake	Voltage	VDC	24							
	Current	ADC	0.21	0.38		0.4	0.75	0.83	1.45	1.67
	Holding Torque	N-m	0.32	1.27		2.55	9.3	7.5	32.0	50.0
		lb-in	2.83	11.24		22.57	82.3	66.38	283.2	442.5
Rotor inertia w/o brake		kg-m2	0.03E-4	0.18E-4	0.34E-4	1.08E-4	2.6E-4	5.98E-4	15.8E-4	43.3E-4
		lb-in-s2	0.27E-4	1.59E-4	3.0E-4	9.56E-4	23.0E-4	52.9E-4	139.8E-4	383.2E-4
Rotor inertia with brake		kg-m2	0.06E-4	0.28E-4	0.44E-4	1.32E-4	3.1E-4	8.8E-4	27.8E-4	56.3E-4
		lb-in-s2	0.53E-4	2.48E-4	3.9E-4	11.7E-4	27.4E-4	77.9E-4	246.0E-4	498.3E-4
Mechanical time constant		ms	0.6	0.9	0.7	0.6	1.7	1.4	1.6	0.9
Static friction torque		N-m	0.02	0.04		0.08	0.49	0.29	0.98	
Torque constant-KT		N-m/A	0.32	0.39	0.4	0.5	0.56	0.91	0.77	0.86
Voltage constant-KE		V/rpm	33.7E-3	41.0E-3	41.6E-3	52.2E-3	58.4E-3	95.71E-3	81.1E-3	90.5E-3
Armature resistance		Ω	20.3	7.5	3.1	1.3	2.052	1.98	0.6	0.162
Armature inductance		mH	32	24	11	6.3	8.4	13.2	6.1	2.3
Electrical time constant		ms	1.6	3.2	3.2	4.8	4.1	6.7	10.1	14.2
Motor Type			Brushless, AC, permanent magnet [Neodymium (Nd), Iron (Fe), Boron (B)]							
Insulation class			Class F							
Insulation resistance			>100 MΩ , 500 VDC							
Insulation strength			1500 VAC, 50 Hz, 60 seconds							
Ambient temperature range			0 to 40°C (32°F to 104°F)							
Operating temperature *(measured case temperature)*			70°C (158°F)							
Maximum operating temperature *(measured case temperature)*			70°C + 40°C = 110°C (230°F)							
Storage temperature			-20 to 65°C (-4 to 149°F)							
Operating humidity			20 to 90% RH (non-condensing)							
Storage humidity			20 to 90% RH (non-condensing)							
Vibration / Shock			2.5G / 5.0G							
Environmental rating			IP65 motor body; IP40 shaft; IP20 connector				IP65 (requires *Sure*Servo cables)			
Weight without brake		kg	0.5	0.9	1.3	2.5	4.7	4.8	12.0	17.0
		lb	1.1	1.98	2.87	5.5	10.36	10.58	26.46	37.48
Weight with brake		kg	0.7	1.4	1.8	3.4	6.3	7.5	19.0	24.0
		lb	1.54	3.09	3.97	7.5	13.89	16.53	41.89	52.9
Agency Approvals			CE; UL recognized (U.S. and Canada)							

NOTE: U.S. customary units are for reference only.

Standard wiring examples

This wiring diagram shows basic wiring only, and additional wiring configurations are possible for some I/O. Refer to the "Installation and Wiring" chapter of the User Manual for more detailed wiring information.

Position (Pr & Pt) Control Modes

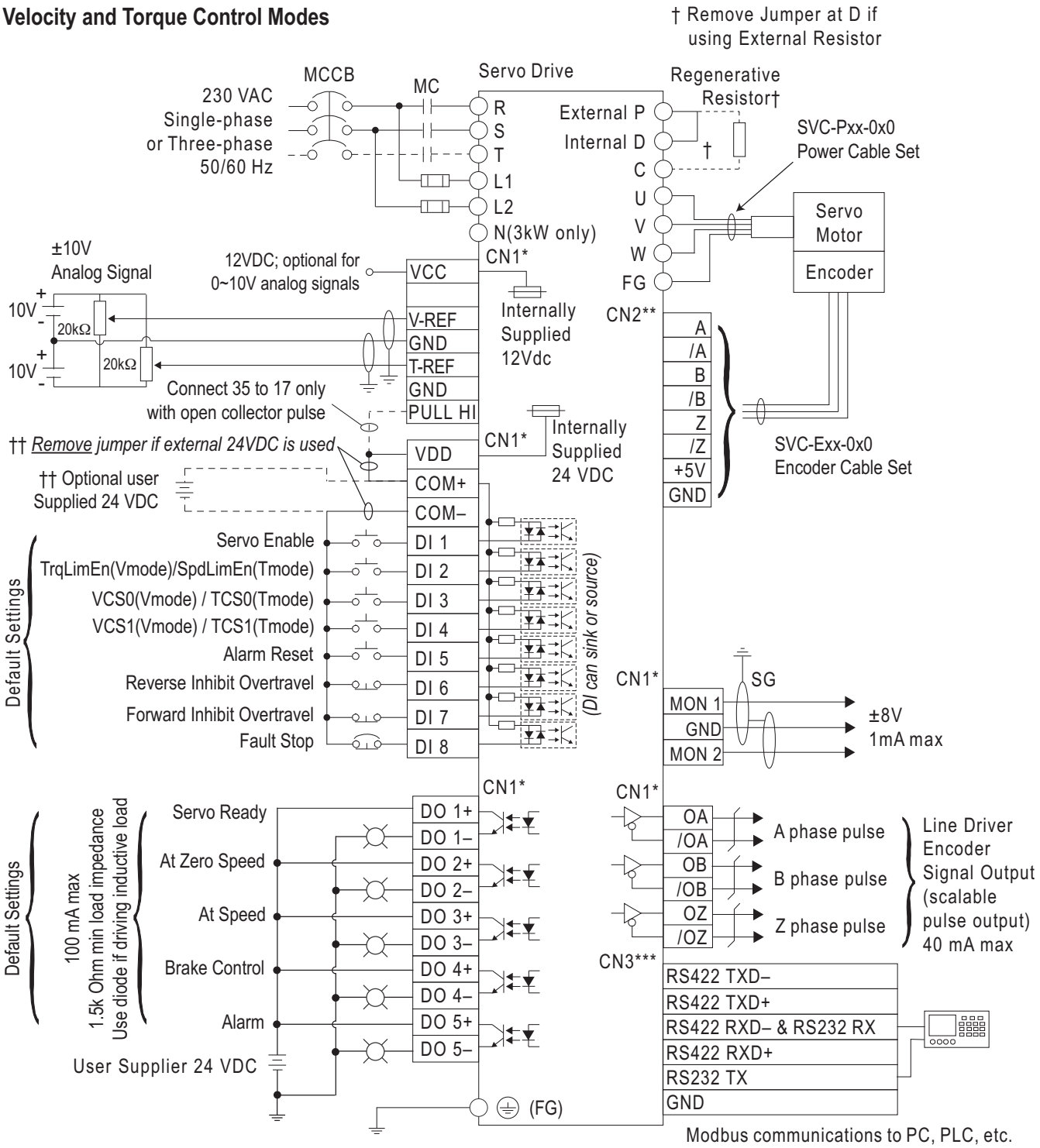


* Use connection kit part #s ZL-RTB50 & ZL-SVC-CBL-50(-x) for CN1 terminal connections.
** Use cable part # SVC-Exx-0x0 for CN2 terminal connections.
*** Use cable part # SVC-MDCOM-CBL for CN3 terminal Modbus network connections.

Standard wiring examples (continued)

THIS WIRING DIAGRAM SHOWS BASIC WIRING ONLY, AND ADDITIONAL WIRING CONFIGURATIONS ARE POSSIBLE FOR SOME I/O. REFER TO THE "INSTALLATION AND WIRING" CHAPTER OF THE USER MANUAL FOR MORE DETAILED WIRING INFORMATION.

Velocity and Torque Control Modes



* Use connection kit part #s ZL-RTB50 & ZL-SVC-CBL-50(-x) for CN1 terminal connections.
** Use cable part # SVC-Exx-0x0 for CN2 terminal connections.
*** Use cable part # SVC-MDCOM-CBL for CN3 terminal Modbus network connections.

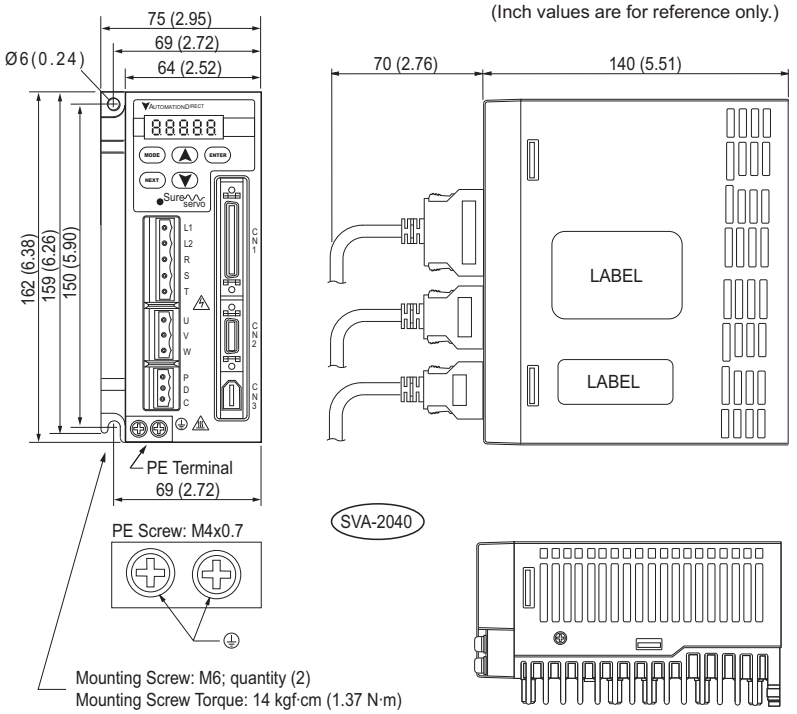
AC Servo System Dimensions

Servo drive dimensions

SVA-2040

RECOMMENDED USER SUPPLIED MOUNTING SCREW IS M6. TIGHTEN TO 14 KGF·CM (1.37 N·M).

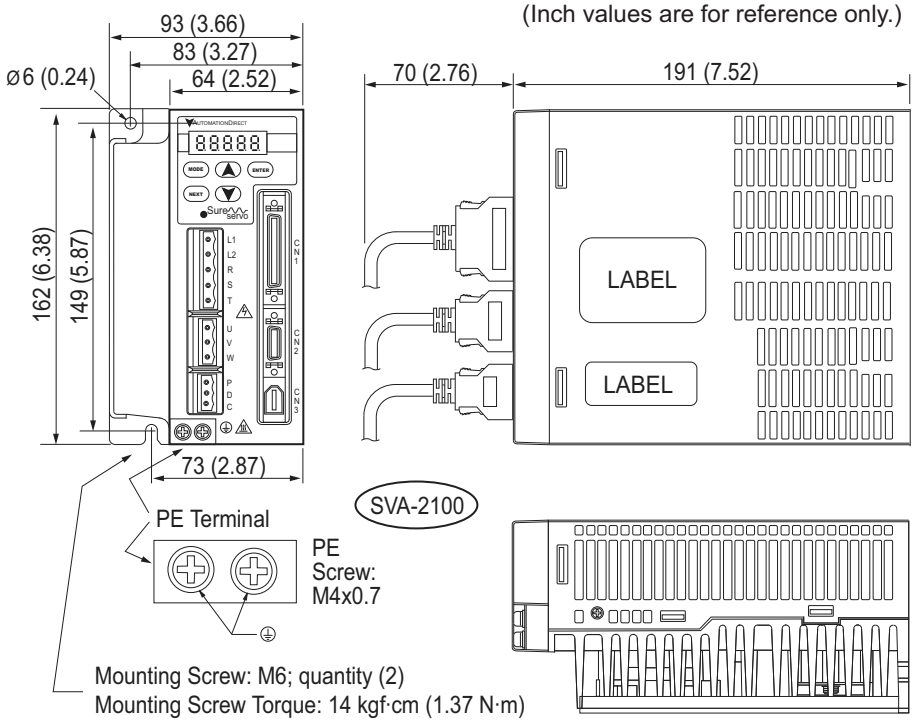
UNITS: mm (in)
(Inch values are for reference only.)



SVA-2100

RECOMMENDED USER SUPPLIED MOUNTING SCREW IS M6. TIGHTEN TO 14 KGF·CM (1.37 N·M).

UNITS: mm (in)
(Inch values are for reference only.)



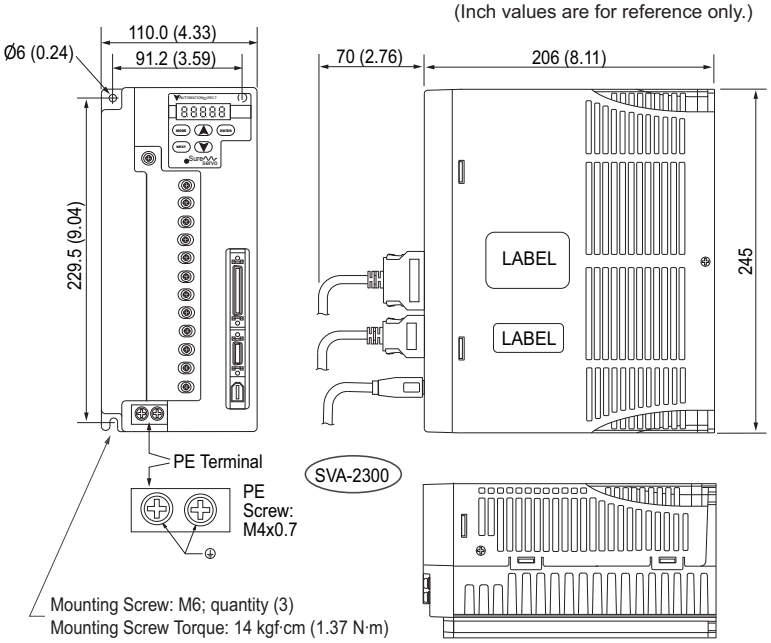
AC Servo System Dimensions

Servo drive dimensions (continued)

SVA-2300

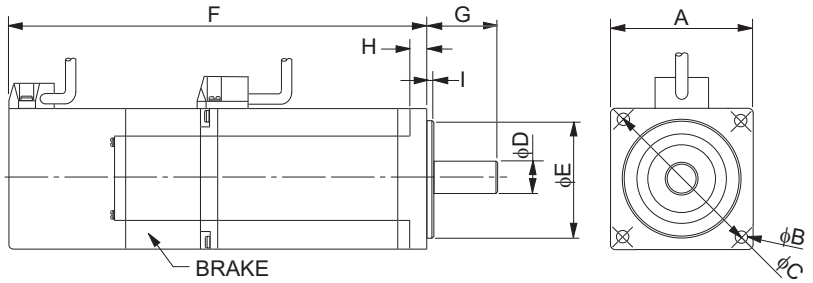
***NOTE:** RECOMMENDED USER SUPPLIED MOUNTING SCREW IS M6. TIGHTEN TO 14 KGF·CM (1.37 N·M).*

UNITS: mm (in)
(Inch values are for reference only.)



Servo motor dimensions

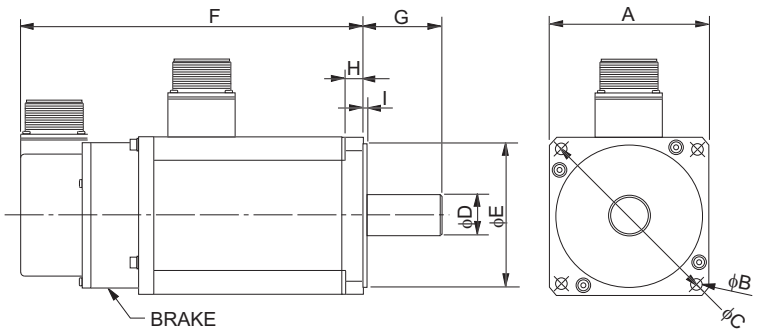
Low inertia models SVL-201(B), SVL-202(B), SVL-SVL-204(B), SVL-207(B)



*Sure*Servo® Motor Dimensions -100W-750W Low Inertia				
Dimension	**SVL-201(B)**	**SVL-202(B)**	**SVL-204(B)**	**SVL-207(B)**
A	40 [1.575]	60 [2.362]		80 [3.15]
B	4.5 [0.1772]	5.5 [0.2165]		6.6 [0.2598]
C	46 [1.811]	70 [2.756]		90 [3.543]
D	8 +0.0/-0.009 (8h6)	14 +0.0/-0.011 (14h6)		19 +0.0 -0.013 (19h6)
E	30 +0.0/-0.021 (30h7)	50 +0.0/-0.025 (50h7)		70 +0.0/-0.030 (70h7)
F (w/o brake)	100.1 [3.941]	102.4 [4.032]	124.4 [4.898]	135 [5.315]
F (with brake)	135.7 [5.343]	137 [5.394]	159 [6.26]	171.6 [6.756]
G	25 [0.98]	30 [1.18]		35 [1.38]
H	5 [0.197]	6 [0.236]		8 [0.315]
I	2.5 [0.098]	3 [0.118]		
Cable length	300mm (12 inches)			
UNITS: mm [in]. (Inches are for reference only; not included on diameter dimensions for accuracy.)				

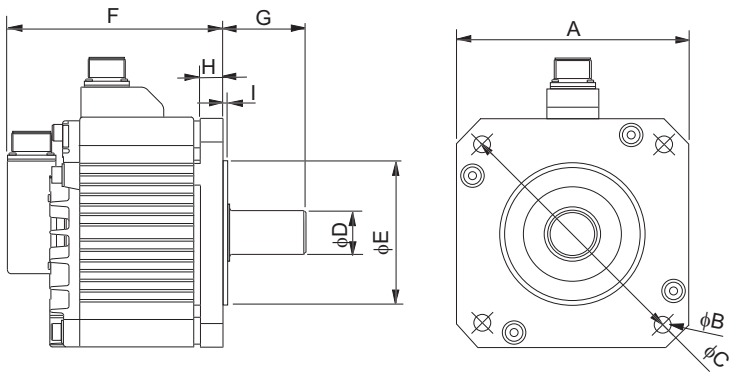
Servo motor dimensions (continued)

Low inertia models SVL-210(B)



*Sure*Servo® Motor Dimensions -1000W Low Inertia	
Dimension	**SVL-210(B)**
A	100 [3.937]
B	9 [0.3543]
C	115 +0.2/-0.2 [4.528]
D	22 +0.0/-0.013 (22h6)
E	95 +0.0/-0.035 (95h7)
F (w/o brake)	158 [6.22]
F (with brake)	190 [7.48]
G	45 [1.77]
H	17 [0.669]
I	7 [0.28]
UNITS: mm [in] (Inches are for reference only; not included on diameter dimensions for accuracy.)	

Medium inertia models SVM-210(B), SVM-220(B), SVM-230(B)



*Sure*Servo® Motor Dimensions -1000W-3000W Medium Inertia			
Dimension	**SVM-210(B)**	**SVM-220(B)**	**SVM-230(B)**
A	130 [5.118]	180 [7.087]	
B	9 [0.3543]	13.5 [0.5315]	
C	145 +0.2/-0.2 [5.709]	200 +0.2/-0.2 [7.874]	
D	22 +0.0/-0.013 (22h6)	35 +0.0/-0.016 (35h6)	
E	110 +0.0/-0.035 (110h7)	114.3 +0/-0.035 (114.3h7)	
F (w/o brake)	143 [5.63]	164 [6.457]	212 [8.35]
F (with brake)	181 [7.126]	213 [8.386]	258 [10.16]
G	55 [2.17]	75 [2.95]	
H	15 [0.591]	20 [0.787]	
I	4 [0.157]		
UNITS: mm [in] (Inches are for reference only; not included on diameter dimensions for accuracy.)			

AC Servo System Accessories

Accessories

External Regeneration Resistors

Use external resistors to provide additional regenerative capacity and to dissipate heat away from the servo drive.

Part Number	Resistance	SureServo Drives	Price
GS-25P0-BR	40Ω	SVA-2040	<--->
GS-2010-BR-ENC	20Ω	SVA-2100, SVA-2300	<--->

Resistor GS-25P0-BR

RF Filter

The RF filter is effective at reducing radiated noise from the motor power cable.

Part Number	Price
RF220X00A	<--->

RF Filter RF220X00A

AC Line Filters

Input EMI filters reduce electromagnetic interference or noise on the input side of the servo drive. They are required for CE compliance and recommended for installations prone to or sensitive to electromagnetic interference.

SureServo® Drives	AC Input Power	EMI Filter Rating	EMI Filter Part Number	Price
SVA-2040	Single-Phase	250V, 1-phase, 20A	20DRT1W3S	<--->
	Three-Phase	250V, 3-phase, 10A	10TDT1W4C	<--->
SVA-2100	Single-Phase	250V, 1-phase, 20A	20DRT1W3S	<--->
	Three-Phase	250V, 3-phase, 10A	10TDT1W4C	<--->
SVA-2300	Three-Phase	250V, 3-phase, 26A	26TDT1W4C	<--->

AC Line Filter 10TD1W4C

Note: *These EMI Filters are electrically compatible with the SureServo drives. However, they are intended to be mounted next to the servo drive. Do not mount the filter under the drive. The drive mounting holes on these units are intended to be used only with AutomationDirect's line of VFDs.*

Edison Fuses & Fuji Contactors

SureServo® Drives	Input Type	Input Voltage	Edison Fuse - Class CC	Price*	Contactor**	Price
SVA-2040	Main Input Power	230V 3-Phase	HCTR4	<--->	SC-E02-xxx	varies
SVA-2100			HCTR7-5	<--->	SC-E03-xxx	varies
SVA-2300			HCTR15	<--->	SC-E04-xxx	varies
SVA-2040		230V 1-phase	HCTR4	<--->	SC-E02-xxx	varies
SVA-2100			HCTR10	<--->	SC-E03-xxx	varies
SVA-2040 SVA-2100 SVA-2300	Control Input Power	230V 1-phase	HCTR2-5	<--->		

Edison Fuse HCTRx

Fuji Contactor SC-E02-xxx

* *Fuses are sold in packages of 10*

** *Note: For contactors, xxx = coil voltage (for example, SC-E02-220VAC).*

Wiring Solutions

Wiring Solutions using the *ZIP*Link Wiring System

*ZIP*Links eliminate the normally tedious process of wiring between devices by utilizing prewired cables and DIN rail mount connector modules. It's as simple as plugging in a cable connector at either end or terminating wires at only one end. Prewired cables keep installation clean and efficient, using half the space at a fraction of the cost of standard terminal blocks. There are several wiring solutions available when using the *ZIP*Link System ranging from PLC I/O-to-*ZIP*Link Connector Modules that are ready for field termination, options for connecting to third party devices, GS, DuraPulse and SureServo Drives, and specialty relay, transorb and communications modules. Pre-printed I/O-specific adhesive label strips for quick marking of *ZIP*Link modules are provided with *ZIP*Link cables. See the following solutions to help determine the best *ZIP*Link system for your application.

Solution 1: DirectLOGIC, CLICK and Productivity3000 I/O Modules to *ZIP*Link Connector Modules

When looking for quick and easy I/O-to-field termination, a *ZIP*Link connector module used in conjunction with a prewired *ZIP*Link cable, consisting of an I/O terminal block at one end and a multi-pin connector at the other end, is the best solution.

Using the PLC I/O Modules to *ZIP*Link Connector Modules selector tables located in this section,

1. Locate your I/O module/PLC.
2. Select a *ZIP*Link Module.
3. Select a corresponding *ZIP*Link Cable.

Solution 2: *Direct*LOGIC, CLICK and Productivity3000 I/O Modules to 3rd Party Devices

When wanting to connect I/O to another device within close proximity of the I/O modules, no extra terminal blocks are necessary when using the *ZIP*Link Pigtail Cables. *ZIP*Link Pigtail Cables are prewired to an I/O terminal block with color-coded pigtail with soldered-tip wires on the other end.

Using the I/O Modules to 3rd Party Devices selector tables located in this section,

1. Locate your PLC I/O module.
2. Select a *ZIP*Link Pigtail Cable that is compatible with your 3rd party device.

Solution 3: GS Series and DuraPulse Drives Communication Cables

Need to communicate via Modbus RTU to a drive or a network of drives?

*ZIP*Link cables are available in a wide range of configurations for connecting to PLCs and *Sure*Servo, *Sure*Step, Stellar Soft Starter and AC drives. Add a *ZIP*Link communications module to quickly and easily set up a multi-device network.

Using the Drives Communication selector tables located in this section,

1. Locate your Drive and type of communications.
2. Select a *ZIP*Link cable and other associated hardware.

Solution 4: Serial Communications Cables

*ZIP*Link offers communications cables for use with *Direct*LOGIC, CLICK, and Productivity3000 CPUs, that can also be used with other communications devices. Connections include a 6-pin RJ12 or 9-pin, 15-pin and 25-pin D-sub connectors which can be used in conjunction with the RJ12 or D-Sub Feedthrough modules.

Using the **Serial Communications Cables** selector table located in this section,

1. Locate your connector type
2. Select a cable.

Solution 5: Specialty *ZIP*Link Modules

For additional application solutions, *ZIP*Link modules are available in a variety of configurations including stand-alone relays, 24VDC and 120VAC transorb modules, D-sub and RJ12 feedthrough modules, communication port adapter and distribution modules, and *Sure*Servo 50-pin I/O interface connection.

Using the ***ZIP*Link Specialty Modules** selector table located in this section,

1. Locate the type of application.
2. Select a ZIPLink module.

Solution 6: *ZIP*Link Connector Modules to 3rd Party Devices

If you need a way to connect your device to terminal blocks without all that wiring time, then our pigtail cables with color-coded soldered-tip wires are a good solution. Used in conjunction with any compatible *ZIP*Link Connector Modules, a pigtail cable keeps wiring clean and easy and reduces troubleshooting time.

Using the **Universal Connector Modules and Pigtail Cables** table located in this section,

1. Select module type.
2. Select the number of pins.
3. Select cable.

Motor Controller Communication

Drive / Motor Controller (GS/DuraPulse/SureServo/SureStep/Stellar) ZIPLink Selector							
Drive / Motor Controller		Communications			ZIPLink Cable		
Controller	Comm Port Type	Network/Protocol	Connects to	Comm Port Type	Cable (2 meter length)	Cable Connectors	Other Hardware Required
GS1	RJ12	RS-485 Modbus RTU	DL06 PLCs	Port 2 (HD15)	GS-485HD15-CBL-2	RJ12 to HD15	–
			D2-260 CPU				–
			GS-EDRV100	RJ12	GS-EDRV-CBL-2	RJ12 to RJ12	–
			ZL-CDM-RJ12Xxx*	RJ12	GS-485RJ12-CBL-2		–
			FA-ISOCON	5-pin Connector	GS-ISOCON-CBL-2	RJ12 to 5-pin plug	–
GS2	RJ12	RS-232 Modbus RTU	CLICK PLCs	Port 2 (RJ12)	GS-RJ12-CBL-2	RJ12 to RJ12	–
			DL05 PLCs				–
			DL06 PLCs	Port 2 (HD15)			FA-15HD
			D2-250-1 CPU				
			D2-260 CPU				
			D4-450 CPU	Port 3 (25-pin)			FA-CABKIT
			P3-550 CPU	Port 2 (RJ12)			–
		RS-485 Modbus RTU	DL06 PLCs	Port 2 (HD15)	GS-485HD15-CBL-2	RJ12 to HD15	–
			D2-260 CPU				–
			GS-EDRV100	RJ12	GS-EDRV-CBL-2	RJ12 to RJ12	–
			ZL-CDM-RJ12Xxx*	RJ12	GS-485RJ12-CBL-2		–
			FA-ISOCON	5-pin Connector	GS-ISOCON-CBL-2	RJ12 to 5-pin plug	–
DuraPulse (GS3)	RJ12	RS-485 Modbus RTU	DL06 PLCs	Port 2 (HD15)	GS-485HD15-CBL-2	RJ12 to HD15	–
			D2-260 CPU				–
			GS-EDRV100	RJ12	GS-EDRV-CBL-2	RJ12 to RJ12	–
			ZL-CDM-RJ12Xxx*	RJ12	GS-485RJ12-CBL-2		–
			FA-ISOCON	5-pin Connector	GS-ISOCON-CBL-2	RJ12 to 5-pin plug	–
SureServo	IEEE1394 (CN3)	RS-232 Modbus RTU	CLICK PLCs	Port 2 (RJ12)	SVC-232RJ12-CBL-2	6-pin IEEE to RJ12	–
			DL05 PLCs				–
			DL06 PLCs	Port 2 (HD15)			FA-15HD
			D2-250-1 CPU				
			D2-260 CPU				
			D4-450 CPU	Port 3 (25-pin)			FA-CABKIT
			P3-550 CPU	Port 2 (RJ12)			–
		RS-485 Modbus RTU	DL06 PLCs	Port 2 (HD15)	SVC-485HD15-CBL-2	6-pin IEEE to HD15	–
			D2-260 CPU				–
			ZL-CDM-RJ12Xxx*	RJ12	SVC-485RJ12-CBL-2	6-pin IEEE to RJ12	–
			USB-485M	RJ45	SVC-485CFG-CBL-2	6-pin IEEE to RJ45	–
Stellar (Soft Starter) SR44 Series	RJ45**	RS-485 Modbus RTU	DL06 PLCs	Port 2 (HD15)	SR44-485HD15-CBL-2	RJ45 to HD15	SR44-RS485**
			D2-250-1 CPU				
			D2-260 CPU				
			ZL-CDM-RJ12Xxx*	RJ12	SR44-485RJ45-CBL-2	RJ45 to RJ12	
SureStep	RJ12	RS-232 ASCII	DL06 PLCs	Port 2 (HD15)	STP-232HD15-CBL-2	HD15-pin to RJ12	–
			D2-250-1 CPU				–
			D2-260 CPU (Port2)				–
			DL05 PLCs	RJ12	STP-232RJ12-CBL-2	RJ12 to RJ12	–
			CLICK PLCs				–

** When using the ZL-CDM-RJ12Xxx ZIPLink Communication Distribution Module, replace the lowercase xx with the number of RJ12 ports, i.e.4 for four ports or10 for ten ports. (ex: ZL-CDM-RJ12X4 or ZL-CDM-RJ12X10)*

*** The SR44-RS485 Communications Adapter must be installed for RS-485 communications with the Stellar soft starters.*